

Exlar SLM/SLG Product Catalog

Rotary Actuators

**CURTISS -
WRIGHT**

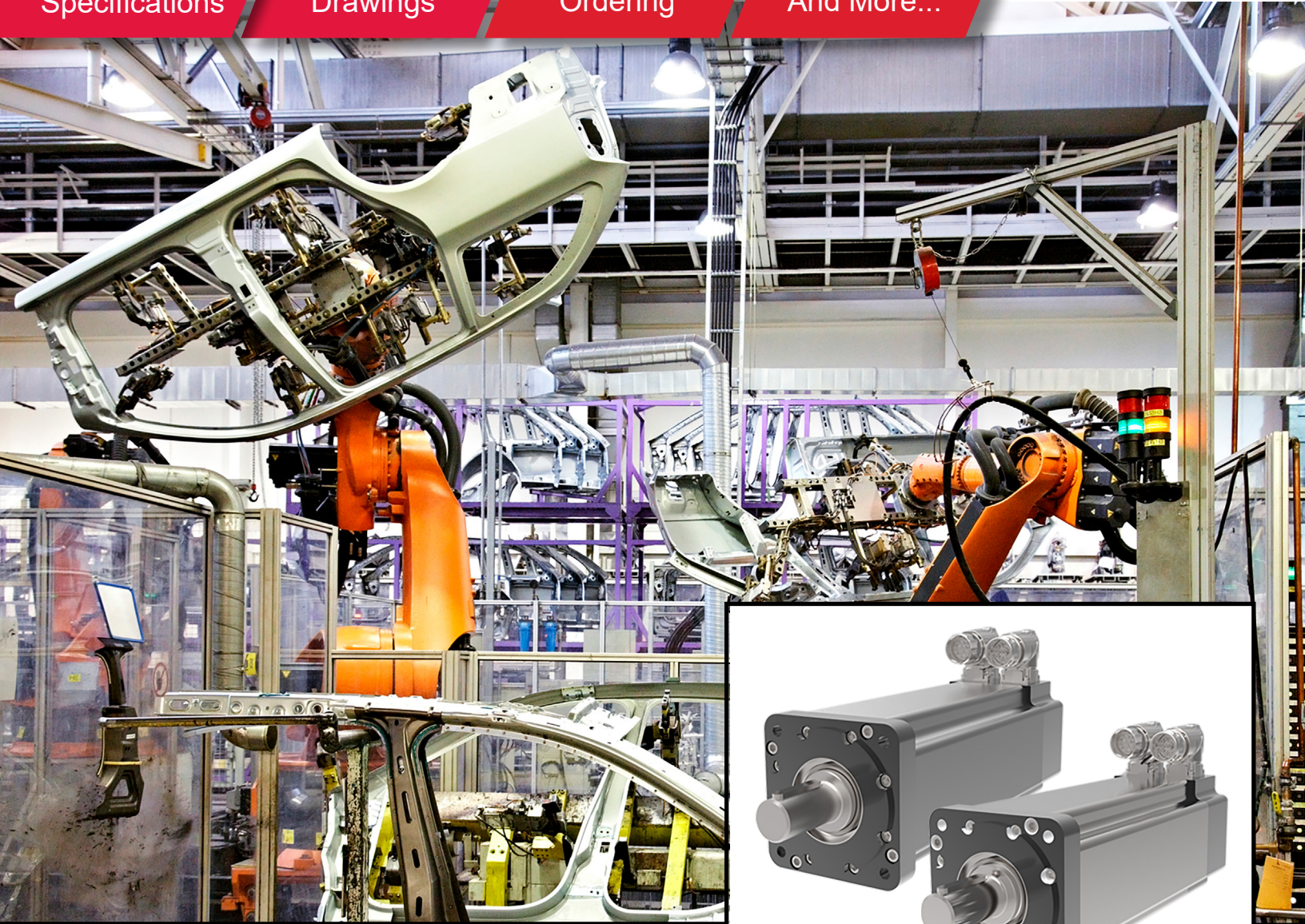
EXLAR®

Specifications

Drawings

Ordering

And More...



SLM/SLG Rotary Actuator

Power | Precision | Proven

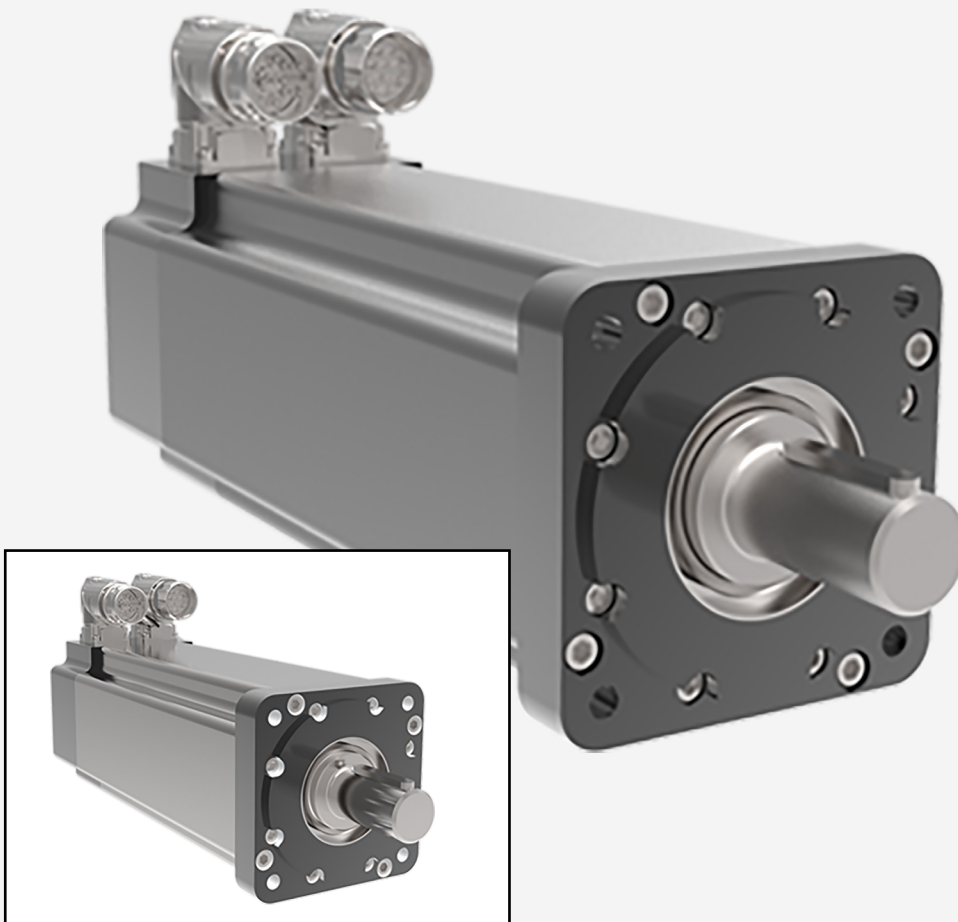
February 2025

SLM/SLG SERIES

BRUSHLESS AC SERVO MOTOR / SERVO GEARMOTOR

Compatible with virtually any manufacturer's servo drive

Multiple frame size options



SLM Series Motors and SLG Series Gearmotors

Description

Brushless servo motor and gearmotor technology from Exlar provides one of the highest torque-to-size ratio available in motion control today. Small size, outstanding performance specifications, quality and customization capabilities offer you the right solution for your motion control application.

Unique T-LAM Stator Design Advantage

This innovative design offers several advantages over traditional motor winding for a more efficient and powerful motor.

Built for durability, T-LAM segmented lamination stator technology consists of individual segments, each containing individual phase wiring for maximum motor performance. The robust insulation, high coercive strength magnets, and complete thermal potting provide a more robust motor design, a design yielding a 35 to 70% torque increase in the same package size! T-LAM motor designs have Class 180H insulation systems and UL recognition.

Very High Torque Density

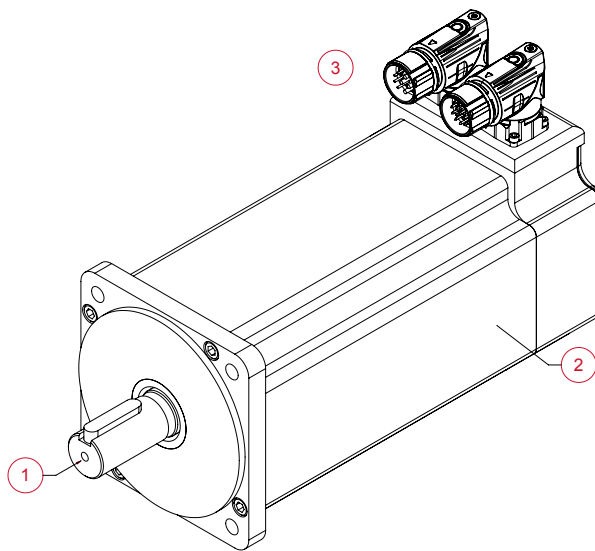
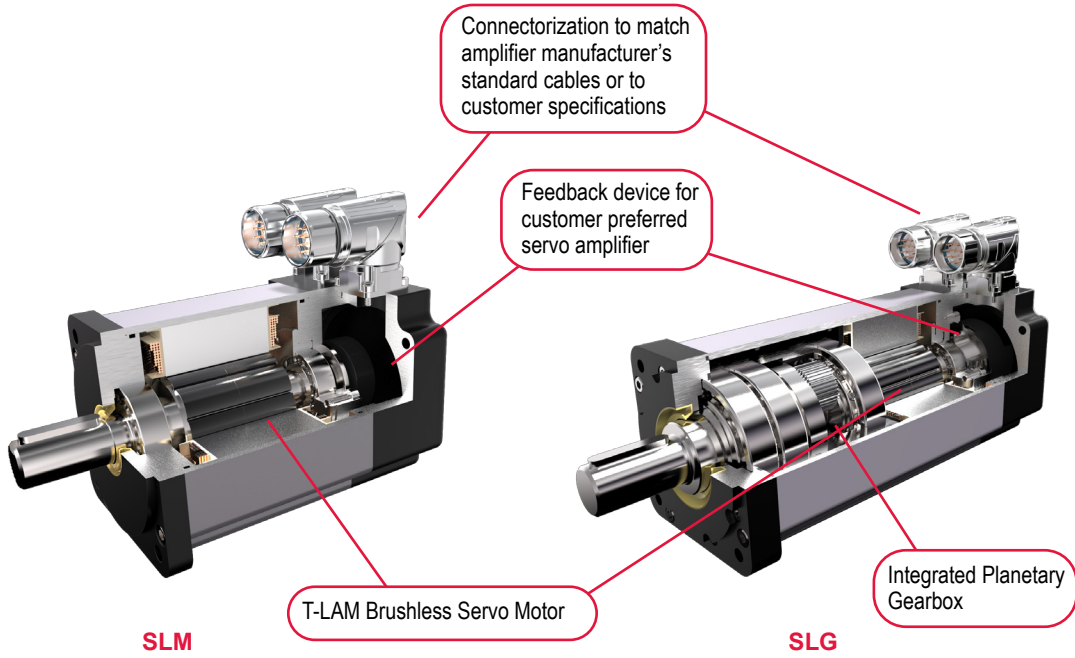
T-LAM technology produces an efficient and powerful motor in a very small package.

- **60 mm SLM060** offers continuous torque up to 15 lbf-in and base speed of 5000 rpm.
- **75 mm SLM075** offers continuous torque up to 36 lbf-in and base speed of 4000 rpm.
- **90 mm SLM090** offers continuous torque up to 56 lbf-in and base speed of 4000 rpm.
- **115 mm SLM115** offers continuous torque up to 176 lbf-in and base speed of 3000 rpm.
- **142 mm SLM142** offers continuous torque up to 237 lbf-in and base speed of 2400 rpm.
- **180 mm SLM180** offers continuous torque up to 612 lbf-in and base speed of 2400 rpm.

Standard Features	
SLM Motor	IP65S sealing
	Right angle rotatable connectors.
	Feedback configurations for nearly all servo amplifiers
	Anodized housings
	Class 180H insulation system
SLG Gearmotor	All features of SLM motor shown above plus...
	High side load bearing design
	Integrated armature and sun gear
	Higher stiffness than bolt-on gearhead and motor
	10 arc minute standard backlash, single stage; 13 arc minute standard backlash, dual stage
	Single and double reduction ratios: 4:1, 5:1, 10:1, 16:1, 20:1, 25:1, 40:1, 50:1, and 100:1

SLM /SLG Rotary Actuators

Product Features



- 1 - Keyed
- 2 - Rear Brake
- 3 - Exlar standard M23 style

Industries and Applications

Automotive

Automotive Assembly

Food Processing

Conveyor Drives

Packaging

Labeling

Machining

Machine tools

Fluid Handling

Winding Machines

Screw Drives

Entertainment / Simulation

Simulation robotics

Animatronics

Medical Equipment

Volumetric pumps

Material Handling

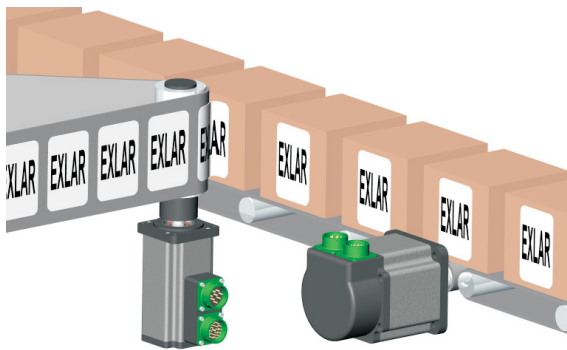
Tensioning

Parts Handling

Web Feed

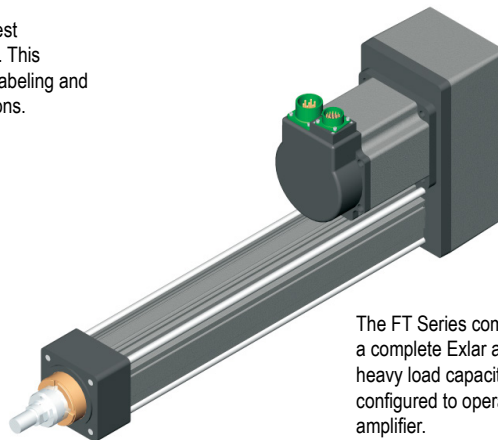
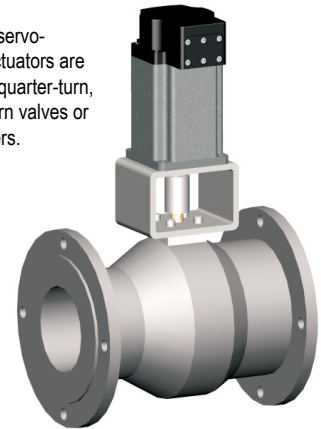
Stage Positioning

Glass Manufacturing



Exlar brushless motors are the highest performance with very compact size. This makes them perfect for high-speed labeling and demanding conveyor drive applications.

Exlar closed-loop, servo-controlled rotary actuators are ideal for operating quarter-turn, full-turn, or multi-turn valves or shaft driven dampers.



The FT Series combined with SLM/G Series motors provides a complete Exlar actuator solution for applications requiring heavy load capacity and high speeds. The motor can be configured to operate with nearly any manufacturer's servo amplifier.

SLM /SLG Rotary Actuators

Electrical and Mechanical Specifications

SLM/SLG060

Motor Stator		118	138	158	168	218	238	258	268	318	338	358	368
Voltage Rating	Vrms	115	230	400	460	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	5000											
RMS SINUSOIDAL COMMUTATION DATA													
Continuous Motor Torque	lbf-in	7.6	7.3	7.0	7.0	11.9	11.5	11.0	11.3	15.0	15.3	14.6	14.9
	Nm	0.86	0.83	0.79	0.79	1.34	1.30	1.25	1.28	1.70	1.73	1.65	1.69
Peak Motor Torque	lbf-in	15.2	14.7	14.0	14.0	23.8	23.0	22.1	22.6	30.0	30.6	29.2	29.9
	Nm	1.72	1.66	1.58	1.58	2.69	2.60	2.49	2.55	3.39	3.46	3.30	3.38
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A	2.5	5.2	7.5	9.5	2.5	5.2	8.6	10.1	2.5	5.3	8.8	10.1
	Nm/A	0.28	0.6	0.9	1.1	0.3	0.6	1.0	1.1	0.3	0.6	1.0	1.1
Continuous Current Rating	A	3.4	1.6	1.0	0.8	5.4	2.5	1.4	1.2	6.6	3.2	1.9	1.6
Peak Current Rating	A	6.9	3.1	2.0	1.6	10.8	4.9	2.9	2.5	13.2	6.5	3.7	3.3
O-PK SINUSOIDAL COMMUTATION DATA													
Continuous Motor Torque	lbf-in	7.6	7.3	7.0	7.0	11.9	11.5	11.0	11.3	15.0	15.3	14.6	14.9
	Nm	0.86	0.83	0.79	0.79	1.34	1.30	1.25	1.28	1.70	1.73	1.65	1.69
Peak Motor Torque	lbf-in	15.2	14.7	14.0	14.0	23.8	23.0	22.1	22.6	30.0	30.6	29.2	29.9
	Nm	1.72	1.66	1.58	1.58	2.69	2.60	2.49	2.55	3.39	3.46	3.30	3.38
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A	1.7	3.7	5.3	6.7	1.7	3.7	6.1	7.2	1.8	3.7	6.2	7.2
	Nm/A	0.20	0.4	0.6	0.8	0.2	0.4	0.7	0.8	0.2	0.4	0.7	0.8
Continuous Current Rating	A	4.9	2.2	1.5	1.2	7.6	3.5	2.0	1.8	9.4	4.6	2.6	2.3
Peak Current Rating	A	9.7	4.5	2.9	2.3	15.2	7.0	4.1	3.5	18.7	9.2	5.3	4.7
MOTOR DATA													
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm	16.9	35.5	51.5	64.8	16.9	35.5	58.6	69.3	17.3	36.0	59.9	69.3
	Vpk/Krpm	23.9	50.2	72.8	91.7	23.9	50.2	82.9	98.0	24.5	50.9	84.8	98.0
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	2.6	12.52	28.82	45.79	1.11	5.26	15.51	20.69	0.76	3.14	9.57	12.22
Inductance (L-L)(+/- 15%)	mH	4.6	21.4	47.9	68.3	2.5	10.2	28.3	39.5	1.7	7.4	18.5	27.4
SLM Armature Inertia (+/- 5%)	lbf-in-sec ²	0.000237				0.000413				0.000589			
	Kg-cm ²	0.268				0.466				0.665			
Brake Inertia	lbf-in-sec ²	0.00012				0.000120				0.000120			
	Kg-cm ²	0.135				0.135				0.135			
Brake Current @ 24 VDC	A	0.33				0.33				0.33			
Brake Holding Torque	lbf-in	19				19				19			
	Nm	2.2				2.2				2.2			
Brake Engage/Disengage Time	ms	14/28				14/28				14/28			
Mechanical Time Constant (tm)	ms	2.20	2.38	2.60	2.61	1.62	1.74	1.89	1.80	1.50	1.45	1.59	1.52
Electrical Time Constant (te)	ms	1.76	1.71	1.66	1.49	2.24	1.95	1.82	1.91	2.27	2.36	1.93	2.24
Friction Torque	lbf-in (Nm)	0.27 (0.031)				0.34 (0.038)				0.38 (0.043)			
Insulation Class		180 (H)											
Insulation System Volt Rating	Vrms	460											
Environmental Rating		IP65S											

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by 0.707 and current by 1.414.

Gearmotor Data

	1 Stack Motor			2 Stack Motor			3 Stack Motor		
SLG Armature Inertia* lbf-in-sec ² (Kg-cm ²)	0.000226 (0.255)			0.000401 (0.453)			0.000576 (0.651)		
GEARING REFLECTED INERTIA	SINGLE REDUCTION						DOUBLE REDUCTION		
	Gear Stages	lbf-in-sec ²	(Kg-cm ²)	Gear Stages	lbf-in-sec ²	(Kg-cm ²)			
	4:1	0.0000132	(0.0149)	16:1	0.0000121	(0.0137)			
	5:1	0.0000087	(0.00984)	20:1, 25:1	0.0000080	(0.00906)			
	10:1	0.0000023	(0.00261)	40:1, 50:1, 100:1	0.0000021	(0.00242)			
Backlash at 1% rated torque	10 Arc minutes Efficiency: Single reduction 91%						13 Arc minutes Double Reduction: 86%		

* Add armature inertia to gearing inertia for total SLG system inertia

Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 1/4" at 25°C ambient

SLM/SLG075

Motor Stator		118	138	158	168	218	238	258	268	318	338	358	368
Voltage Rating	Vrms	115	230	400	460	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	4000											
RMS SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in	16.6	16.4	16.3	16.0	26.0	26.4	26.2	26.4	37.9	35.9	37.3	36.4
	Nm	1.88	1.85	1.84	1.81	2.94	2.89	2.96	2.98	4.29	4.05	4.21	4.12
Peak Motor Torque	lbf-in	33.3	32.8	32.6	32.1	52.0	52.7	52.4	52.8	75.9	71.7	74.6	72.9
	Nm	3.76	3.70	3.68	3.62	5.88	5.96	5.92	5.96	8.57	8.10	8.43	8.23
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A	3.4	6.6	12.5	13.1	3.7	6.8	11.6	13.5	3.4	6.8	11.6	13.9
	Nm/A	0.4	0.7	1.4	1.5	0.4	0.8	1.3	1.5	0.4	0.8	1.3	1.6
Continuous Current Rating	A	5.5	2.8	1.5	1.4	7.9	4.4	2.5	2.2	12.5	5.9	3.6	2.9
Peak Current Rating	A	11.0	5.6	2.9	2.7	15.9	8.7	5.1	4.4	25.1	11.8	7.2	5.8
O-PEAK SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in	16.6	16.4	16.3	16.0	26.0	26.4	26.2	26.4	37.9	35.9	37.3	36.4
	Nm	1.88	1.85	1.84	1.81	2.94	2.98	2.96	2.98	4.29	4.05	4.21	4.12
Peak Motor Torque	lbf-in	33.3	32.8	32.6	32.1	52.0	52.7	52.4	52.8	75.9	71.7	74.6	72.9
	Nm	3.76	3.70	3.68	3.62	5.88	5.96	5.92	5.96	8.57	8.10	8.43	8.23
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A	2.4	4.6	8.8	9.3	2.6	4.8	8.2	9.6	2.4	4.8	8.2	9.9
	Nm/A	0.3	0.5	1.0	1.0	0.3	0.5	0.9	1.1	0.3	0.5	0.9	1.1
Continuous Current Rating	A	7.8	4.0	2.1	1.9	11.2	6.2	3.6	3.1	17.7	8.4	5.1	4.1
Peak Current Rating	A	15.6	7.9	4.1	3.9	22.4	12.3	7.2	6.2	35.5	16.8	10.1	8.3
MOTOR STATOR DATA													
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm	23.1	44.7	85.2	89.5	25.0	46.2	78.9	92.4	23.1	46.2	79.4	95.3
	Vpk/Krpm	32.7	63.3	120.4	126.5	35.4	65.3	111.6	130.6	32.7	65.3	112.3	134.7
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	1.66	6.42	23.49	26.84	0.83	2.75	8.15	11.01	0.40	1.77	4.83	7.29
Inductance (L-L)(+/- 15%)	mH	4.6	17.3	62.6	69.2	2.6	8.8	25.7	35.2	1.4	5.8	17.0	24.5
SLM Armature Inertia	lbf-in-sec ² (+/- 5%)	0.00054				0.00097				0.00140			
	Kg-cm ²	0.616				1.100				1.583			
Brake Inertia	lbf-in-sec ²	0.000159				0.000159				0.000159			
	Kg-cm ²	0.18				0.18				0.18			
Brake Current @ 25 VDC	A	0.5				0.5				0.5			
Brake Holding Torque	lbf-in	40				40				40			
	Nm	4.5				4.5				4.5			
Brake Engage/Disengage Time	ms	9/35				9/35				9/35			
Mechanical Time Constant (tm)	ms	1.71	1.77	1.79	1.85	1.31	1.27	1.29	1.27	1.05	1.18	1.09	1.14
Electrical Time Constant (te)	ms	2.78	2.69	2.67	2.58	3.11	3.19	3.15	3.20	3.65	3.26	3.53	3.37
Friction Torque	lbf-in (Nm)	0.51 (0.058)				0.67 (0.075)				0.90 (0.101)			
Insulation Class		180 (H)											
Insulation System Volt Rating	Vrms	460											
Environmental Rating		IP65S											

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by 0.707 and current by 1.414.

Gearmotor Data

	1 Stack Motor	2 Stack Motor	3 Stack Motor
SLG Armature Inertia [*] lbf-in-sec ² (Kg-cm ²)	0.000660 (0.7450)	0.001068 (1.2057)	0.001494 (1.6868)
SLM Armature Inertia [*] lbf-in-sec ² (Kg-cm ²)	0.000545 (0.6158)	0.000973 (1.0996)	0.001401 (1.5834)
GEARING REFLECTED INERTIA			
	SINGLE REDUCTION		
	Gear Stages	lbf-in-sec ²	(Kg-cm ²)
	4:1	0.0000947	(0.1069)
	5:1	0.0000617	(0.0696)
	10:1	0.0000165	(0.0186)
Backlash at 1% rated torque	10 Arc minutes Efficiency: Single reduction 91%		

* Add armature inertia to gearing inertia for total SLG system inertia

Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 3/8" at 25°C ambient

SLM /SLG Rotary Actuators

SLM/SLG090

Motor Stator		118	138	158	168	218	238	258	268	338	358	368	
Voltage Rating	Vrms	115	230	400	460	115	230	400	460	230	400	460	
Speed @ Bus Voltage	rpm	4000											
RMS SINUSOIDAL COMMUTATION DATA													
Continuous Motor Torque	lbf-in	23.8	24.0	23.7	24.7	39.6	40.0	39.5	39.9	55.7	55.4	55.7	
	Nm	2.68	2.71	2.67	2.79	4.47	4.52	4.46	4.51	6.30	6.26	6.30	
Peak Motor Torque	lbf-in	47.5	48.0	47.3	49.4	79.1	80.0	79.0	79.9	111.5	110.9	111.5	
	Nm	5.37	5.42	5.35	5.58	8.94	9.04	8.93	9.02	12.59	12.52	12.59	
Torque Constant (Kt) (+/- 10% @ 25 C)	lbf-in/A	3.2	6.6	11.6	13.2	3.2	6.6	11.6	13.2	6.6	11.6	13.1	
	Nm/A	0.37	0.7	1.3	1.5	0.4	0.7	1.3	1.5	0.7	1.3	1.5	
Continuous Current Rating	A	8.2	4.0	2.3	2.1	13.6	6.8	3.8	3.4	9.5	5.3	4.8	
Peak Current Rating	A	16.4	8.1	4.6	4.2	27.3	13.5	7.6	6.7	19.0	10.7	9.5	
O-PK SINUSOIDAL COMMUTATION DATA													
Continuous Motor Torque	lbf-in	23.8	24.0	23.7	24.7	39.6	40.0	39.5	39.9	55.7	55.4	55.7	
	Nm	2.68	2.71	2.67	2.79	4.47	4.52	4.46	4.51	6.30	6.26	6.30	
Peak Motor Torque	lbf-in	47.5	48.0	47.3	49.4	79.1	80.0	79.0	79.9	111.5	110.9	111.5	
	Nm	5.37	5.42	5.35	5.58	8.94	9.04	8.93	9.02	12.59	12.52	12.59	
Torque Constant (Kt) (+/- 10% @ 25 C)	lbf-in/A	2.3	4.7	8.2	9.4	2.3	4.7	8.2	9.4	4.6	8.2	9.3	
	Nm/A	0.26	0.5	0.9	1.1	0.3	0.5	0.9	1.1	0.5	0.9	1.0	
Continuous Current Rating	A	11.6	5.7	3.2	2.9	19.3	9.5	5.4	4.8	13.4	7.5	6.7	
Peak Current Rating	A	23.2	11.4	6.5	5.9	38.6	19.1	10.8	9.5	26.9	15.1	13.4	
MOTOR DATA													
Voltage Constant (Ke) (+/- 10% @ 25 C)	Vrms/Krpm	22.1	45.2	78.9	90.4	22.1	45.2	78.9	90.4	44.7	79.4	89.5	
	Vpk/Krpm	31.3	64.0	111.6	127.9	31.3	64.0	111.6	127.9	63.3	112.3	126.5	
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	
Resistance (L-L)(+/- 5% @ 25 C)	Ohms	0.75	3.06	9.57	11.55	0.30	1.21	3.78	4.86	0.69	2.19	2.75	
Inductance (L-L)(+/- 15%)	mH	6.1	25.6	78.0	88.6	2.9	10.5	37.2	43.1	6.6	24.7	31.4	
SLM Armature Inertia (+/- 5%)	lbf-in-sec ²	0.00054				0.00097				0.00140			
	Kg-cm ²	0.609				1.09				1.58			
Brake Inertia	lbf-in-sec ²	0.00096				0.00096				0.00096			
	Kg-cm ²	1.08				1.08				1.08			
Brake Current @ 24 VDC	A	0.67				0.67				0.67			
Brake Holding Torque	lbf-in (Nm)	97 (11)				97 (11)				97 (11)			
Brake Engage/Disengage Time	ms	20/29				20/29				20/29			
Mechanical Time Constant (tm)	ms	0.83	0.82	0.84	0.77	0.59	0.58	0.59	0.58	0.48	0.49	0.48	
Electrical Time Constant (te)	ms	8.21	7.31	8.14	7.67	9.88	8.66	9.85	8.88	9.57	11.30	11.43	
Friction Torque	lbf-in (Nm)	0.68 (0.077)				0.85 (0.095)				1.06 (0.119)			
Insulation Class		180 (H)											
Insulation System Volt Rating	Vrms	460											
Environmental Rating		IP65S											

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by 0.707 and current by 1.414.

Gearmotor Data

	1 Stack Motor			2 Stack Motor			3 Stack Motor					
SLG Armature Inertia* lbf-in-sec ² (Kg-cm ²)	0.00114 (1.29)			0.00157 (1.77)			0.00200 (2.26)					
GEARING REFLECTED INERTIA	SINGLE REDUCTION						DOUBLE REDUCTION					
	Gear Stages		lbf-in-sec ²		(Kg-cm ²)		Gear Stages		lbf-in-sec ²		(Kg-cm ²)	
	4:1		0.000154		(0.174)		16:1		0.000115		(0.130)	
	5:1		0.000100		(0.113)		20:1, 25:1		0.0000756		(0.0854)	
10:1		0.0000265		(0.0300)		40:1, 50:1, 100:1		0.0000203		(0.0230)		
Backlash at 1% rated torque	10 Arc minutes Efficiency: Single reduction 91%						13 Arc minutes Double Reduction: 86%					

* Add armature inertia to gearing inertia for total SLG system inertia

Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 3/8" at 25°C ambient

SLM/SLG115

Motor Stator		118	138	158	168	238	258	268	338	358	368		
Voltage Rating	Vrms	115	230	400	460	230	400	460	230	400	460		
Speed @ Bus Voltage	rpm	3000											
RMS SINUSOIDAL COMMUTATION DATA													
Continuous Motor Torque	lbf-in	74.1	74.1	74.3	74.1	123.6	121.4	123.8	172.3	168.9	176.9		
	Nm	8.37	8.37	8.39	8.37	13.96	13.72	13.96	19.46	19.09	19.98		
Peak Motor Torque	lbf-in	148.2	148.2	148.6	148.1	247.2	242.8	247.2	344.5	337.8	353.7		
	Nm	16.74	16.74	16.79	16.74	27.93	27.43	27.93	38.93	38.17	39.96		
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A	4.3	8.7	15.7	17.3	8.7	15.8	17.3	8.5	15.8	17.5		
	Nm/A	0.49	1.0	1.8	2.0	1.0	1.8	2.0	1.0	1.8	2.0		
Continuous Current Rating	A	19.1	9.5	5.3	4.8	15.9	8.6	8.0	22.7	11.9	11.3		
Peak Current Rating	A	38.2	19.1	10.6	9.5	31.8	17.1	15.9	45.4	23.8	22.5		
O-PK SINUSOIDAL COMMUTATION DATA													
Continuous Motor Torque	lbf-in	74.1	74.1	74.3	74.1	123.6	121.4	123.6	172.3	168.9	176.9		
	Nm	8.37	8.37	8.39	8.37	13.96	13.72	13.96	19.46	19.09	19.98		
Peak Motor Torque	lbf-in	148.2	148.2	148.6	148.1	247.2	242.8	247.2	344.5	337.8	353.7		
	Nm	16.74	16.74	16.79	16.74	27.93	27.43	27.93	38.93	38.17	39.96		
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A	3.1	6.1	11.1	12.3	6.1	11.2	12.3	6.0	11.2	12.4		
	(Nm/A)	0.35	0.7	1.3	1.4	0.7	1.3	1.4	0.7	1.3	1.4		
Continuous Current Rating	A	27.0	13.5	7.5	6.7	22.5	12.1	11.3	32.1	16.9	15.9		
Peak Current Rating	A	54.0	27.0	15.0	13.5	45.0	24.2	22.5	64.2	33.7	31.9		
MOTOR DATA													
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm	29.6	59.2	106.9	118.5	59.2	108.2	118.5	58.0	108.2	119.8		
	Vpk/Krpm	41.9	83.8	151.2	167.6	83.8	153.0	167.6	82.0	153.0	169.4		
Pole Configuration		8	8	8	8	8	8	8	8	8	8		
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	0.20	0.80	2.60	3.21	0.34	1.17	1.35	0.20	0.72	0.81		
Inductance (L-L)(+/- 15%)	mH	3.3	13.0	42.4	52.1	5.9	21.1	25.3	4.0	13.1	17.1		
SLM Armature Inertia (+/- 5%)	lbf-in-sec ²	0.00342				0.00620				0.00899			
	Kg-cm ²	3.86				7.00				10.14			
Brake Inertia	lbf-in-sec ²	0.00327				0.00327				0.00327			
	Kg-cm ²	3.70				3.70				3.70			
Brake Current @ 24 VDC	A	0.75				0.75				0.75			
Brake Holding Torque	lbf-in (Nm)	195 (22)				195 (22)				195 (22)			
Brake Engage/Disengage Time	ms	25/50				25/50				25/50			
Mechanical Time Constant (tm)	ms	0.80	0.80	0.79	0.80	0.61	0.63	0.61	0.54	0.56	0.51		
Electrical Time Constant (te)	ms	16.26	16.26	16.34	16.25	17.6	18.06	18.72	18.5	18.14	21.16		
Friction Torque	lbf-in (Nm)	1.43 (0.16)				1.81 (0.204)				2.32 (0.262)			
Insulation Class		180 (H)											
Insulation System Volt Rating	Vrms	460											
Environmental Rating		IP65S											

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by 0.707 and current by 1.414.

Gearmotor Data

	1 Stack Motor			2 Stack Motor			3 Stack Motor					
SLG Armature Inertia ^a lbf-in-sec ² (Kg-cm ²)	0.00662 (7.47)			0.00945 (10.67)			0.01228 (13.86)					
GEARING REFLECTED INERTIA	SINGLE REDUCTION						DOUBLE REDUCTION					
	Gear Stages		lbf-in-sec ²	(Kg-cm ²)	Gear Stages		lbf-in-sec ²	(Kg-cm ²)				
	4:1		0.000895	(1.010)	16:1		0.000513	(0.579)				
	5:1		0.000585	(0.660)	20:1, 25:1		0.000346	(0.391)				
	10:1		0.000152	(0.172)	40:1, 50:1, 100:1		0.000092	(0.104)				
Backlash at 1% rated torque	10 Arc minutes Efficiency: Single reduction 91%						13 Arc minutes Double Reduction: 86%					

^a Add armature inertia to gearing inertia for total SLG system inertia

Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2" at 25°C ambient

SLM /SLG Rotary Actuators

SLM142

Motor Stator		118	138	158	168	238	258	268	358	368
Bus Voltage	Vrms	115	230	400	460	230	400	460	400	460
Speed @ Bus Voltage	RPM	2400								
RMS SINUSOIDAL COMMUTATION DATA										
Continuous Motor Torque	lbf-in	108.5	107.2	104.8	109.4	179.9	178.8	177.8	237.2	238.3
	Nm	12.25	(2.12)	11.84	12.36	20.32	20.20	20.09	26.80	26.93
Peak Motor Torque	lbf-in	216.9	214.5	209.5	218.8	359.8	357.6	355.7	474.4	476.7
	Nm	24.51	24.23	23.67	24.72	40.65	40.40	40.19	53.60	53.85
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A	5.9	11.8	20.2	23.6	11.8	20.2	23.6	20.2	24.0
	Nm/A	0.67	1.3	2.3	2.7	1.3	2.3	2.7	2.3	2.7
Continuous Current Rating	A	20.5	10.2	5.8	5.2	17.0	9.9	8.4	13.1	11.1
Peak Current Rating	A	41.1	20.3	11.6	10.4	34.1	19.8	16.8	26.2	22.2
O-PK SINUSOIDAL COMMUTATION DATA										
Continuous Motor Torque	lbf-in	108.5	107.2	104.8	109.4	179.9	178.8	177.8	237.2	238.3
	Nm	12.25	12.12	11.84	12.36	20.32	20.20	20.09	26.80	26.93
Peak Motor Torque	lbf-in	216.9	214.5	209.5	218.8	359.8	357.6	355.7	474.4	476.7
	Nm	24.51	24.23	23.67	24.72	40.65	40.40	40.19	53.60	53.85
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A	4.2	8.3	14.3	16.7	8.3	14.3	16.7	14.3	17.0
	Nm/A	0.47	0.9	1.6	1.9	0.9	1.6	1.9	1.6	1.9
Continuous Current Rating	A	29.1	14.4	8.2	7.3	24.1	14.0	11.9	18.5	15.7
Peak Current Rating	A	58.1	28.7	16.4	14.7	48.2	27.9	23.8	37.1	31.4
MOTOR DATA										
Voltage Constant (Ke)	Vrms/Krpm	40.3	80.6	138.1	161.1	80.6	138.1	161.1	138.1	164.0
(+/- 10% @ 25°C)	Vpk/Krpm	57.0	113.9	195.3	227.9	113.9	195.3	227.9	195.3	232.0
Pole Configuration		8	8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	0.21	0.87	2.68	3.34	0.339	1.01	1.39	0.61	0.858
Inductance (L-L)(+/- 15%)	mH	5.4	21.7	63.9	78.3	10.4	27.6	41.5	20.0	28.2
Armature Inertia (+/- 5%)	lb-in-sec ²	0.00927				0.01537			0.02146	
	Kg-cm ²	10.47				17.363			24.249	
Brake Inertia	lb-in-sec ²	0.008408				0.008408			0.008408	
	Kg-cm ²	9.5				9.5			9.5	
Brake Current @ 24 VDC	A	1.0				1.0			1.0	
Brake Holding Torque	lbf-in (Nm)	354 (39.99)				354 (39.99)			354 (39.99)	
Brake Engage/Disengage Time	ms	25/73				25/73			25/73	
Mechanical Time Constant (tm)	ms	1.23	1.26	1.32	1.21	0.81	0.82	0.83	0.70	0.69
Electrical Time Constant (te)	ms	25.59	25.02	23.88	23.43	30.58	27.30	29.89	32.60	32.90
Friction Torque	lbf-in (Nm)	2.07 (0.234)				2.65 (0.299)			3.32 (0.375)	
Insulation Class		180 (H)								
Insulation System Volt Rating	Vrms	460								
Environmental Rating		IP65S								

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by 0.707 and current by 1.414.
Gearmotor not available on 142 frame motor.

Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2" at 25°C ambient

SLM180

Motor Stator		138	158	168	238	258	268	358	368
Bus Voltage	Vrms	230	400	460	230	400	460	400	460
Speed @ Bus Voltage	RPM	2400							
RMS SINUSOIDAL COMMUTATION DATA									
Continuous Motor Torque	lbf-in	254.2	249.9	261.9	424.8	423.0	427.5	595.6	611.6
	Nm	28.72	28.23	29.59	47.99	47.79	48.30	67.29	69.10
Peak Motor Torque	lbf-in	508.4	499.8	523.8	849.6	846.0	855.1	1,191.2	1,223.2
	Nm	57.44	56.47	59.18	95.99	95.59	96.61	134.58	138.19
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A	12.6	21.8	25.2	12.6	21.8	25.2	21.4	25.2
	Nm/A	1.4	2.5	2.8	1.4	2.5	2.8	2.4	2.8
Continuous Current Rating (IG)	A	22.6	12.8	11.6	37.7	21.7	19.0	31.1	27.2
Peak Current Rating	A	45.2	25.6	23.3	75.5	43.4	38.0	62.2	54.3
O-PK SINUSOIDAL COMMUTATION DATA									
Continuous Motor Torque	lbf-in	254.2	249.9	261.9	424.8	423.0	427.5	595.6	611.6
	Nm	28.72	28.23	29.59	47.99	47.79	48.30	67.29	69.10
Peak Motor Torque	lbf-in	508.4	499.8	523.8	849.6	846.0	855.1	1,191.2	1,223.2
	Nm	57.44	56.47	59.18	95.99	95.59	96.61	134.58	138.19
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A	8.9	15.4	17.8	8.9	15.4	17.8	15.1	17.8
	Nm/A	1.0	1.7	2.0	1.0	1.7	2.0	1.7	2.0
Continuous Current Rating	A	31.9	18.1	16.4	53.4	30.7	26.8	44.0	38.4
Peak Current Rating	A	63.9	36.2	32.9	106.7	61.3	53.7	88.0	76.8
MOTOR STATOR DATA									
Voltage Constant (Ke)	Vrms/Krpm	85.9	148.9	171.8	85.9	148.9	171.8	146.1	171.8
(+/- 10% @ 25°C)	Vpk/Krpm	121.5	210.6	243.0	121.5	210.6	243.0	206.6	243.0
Pole Configuration		8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	0.325	1.010	1.224	0.134	0.407	0.530	0.233	0.306
Inductance (L-L)(+/- 15%)	mH	8.3	24.8	29.4	3.9	11.8	15.8	7.5	10.3
Armature Inertia (+/- 5%)	lb-in-sec ²	0.05051			0.08599			0.12147	
	Kg-cm ²	57.071			97.159			137.246	
Brake Inertia	lb-in-sec ²	0.02815							
	Kg-cm ²	31.8							
Brake Current @ 24 VDC	A	1.45							
Brake Holding Torque	lbf-in (Nm)	708 (80)							
Brake Engage/Disengage Time	ms	53/97							
Mechanical Time Constant (tm)	ms	2.25	2.33	2.12	1.58	1.59	1.56	1.34	1.27
Electrical Time Constant (te)	ms	25.44	24.58	24.03	29.38	29.14	29.76	32.07	33.81
Friction Torque	lbf-in (Nm)	5.07 (0.573)			7.80 (0.881)			11.52 (1.302)	
Insulation Class		180 (H)							
Insulation System Volt Rating	Vrms	460							
Thermal Switch, Case Temp	deg C	100							
Environmental Rating		IP65S							

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by 0.707 and current by 1.414.
Gearmotor not available on 180 frame.

Test data derived using NEMA recommended aluminum heatsink 16" x 16" x 1" at 25°C ambient

SLM /SLG Rotary Actuators

SLG Series Gearmotor General Performance Specifications

Two torque ratings for the SLG Series Gearmotors are given in the table below. The left hand columns give the maximum (peak) allowable output torque for the indicated ratios of each size SLG Series Gearmotor. This is NOT the rated output torque of the motor multiplied by the ratio of the reducer.

It is possible to select a configuration of the motor selection and gear ratio such that the rated motor torque, multiplied by the gear ratio exceeds these ratings. It is the responsibility of the user to ensure that the settings of the system, including the amplifier, do not allow these values to be exceeded.

The right hand columns give the output torque at the indicated speed which will result in 10,000 hour (L10). The setup of the system, including the amplifier, will determine the actual output torque and speed.

SLM Radial Load

RPM	50	100	250	500	1000	3000
SLM060 lbf (N)	250 (1112)	198 (881)	148 (658)	116 (516)	92 (409)	64 (285)
SLM075 lbf (N)	278 (1237)	220 (979)	162 (721)	129 (574)	102 (454)	71 (316)
SLM090 lbf (N)	427 (1899)	340 (1512)	250 (1112)	198 (881)	158 (703)	109 (485)
SLM115 lbf (N)	579 (2576)	460 (2046)	339 (1508)	269 (1197)	214 (952)	148 (658)
SLM142 lbf (N)	1367 (6081)	1085 (4826)	800 (3559)	635 (2825)	504 (2242)	349 (1552)
SLM180 lbf (N)	2237 (9951)	1776 (7900)	1308 (5818)	1038 (4617)	824 (3665)	605 (2691)

SLG Radial Load

RPM	50	100	250	500	1000	3000
SLG060 lbf (N)	189 (841)	150 (667)	110 (489)	88 (391)	70 (311)	48 (214)
SLG075 lbf (N)	343 (1526)	272 (1210)	200 (890)	159 (707)	126 (560)	88 (391)
SLG090 lbf (N)	350 (1557)	278 (1237)	205 (912)	163 (725)	129 (574)	89 (396)
SLG115 lbf (N)	858 (3817)	681 (3029)	502 (2233)	398 (1770)	316 (1406)	218 (970)

Side load ratings shown above are for 10,000 hour bearing life at 25 mm from motor face at given rpm.

Output Torque Ratings–Mechanical

Model	Ratio	Maximum Allowable Output Torque Set by User- lbf-in (Nm)	Output Torque @ Speed for 10,000 Hour Life – lbf-in (Nm)		
			1000 RPM	3000 RPM	5000 RPM
SLG060	4:1	603 (68.1)	144 (16.2)	104 (11.7)	88 (9.9)
	5:1	522 (58.9)	170 (19.2)	125 (14.1)	105 (11.9)
	10:1	327 (36.9)	200 (22.6)	140 (15.8)	120 (13.6)
	16:1	603 (68.1)	224 (25.3)	160 (18.1)	136 (15.4)
	20:1	603 (68.1)	240 (27.1)	170 (19.2)	146 (16.5)
	25:1	522 (58.9)	275 (31.1)	200 (22.6)	180 (20.3)
	40:1	603 (68.1)	288 (32.5)	208 (23.5)	180 (20.3)
	50:1	522 (58.9)	340 (38.4)	245 (27.7)	210 (23.7)
	100:1	327 (36.9)	320 (36.1)	280 (31.6)	240 (27.1)
			1000 RPM	2500 RPM	4000 RPM
SLG075	4:1	1618 (182.3)	384 (43.4)	292 (32.9)	254 (23.7)
	5:1	1446 (163.4)	395 (44.6)	300 (33.9)	260 (29.4)
	10:1	700 (79.1)	449 (50.7)	341 (38.5)	296 (33.4)
			1000 RPM	2500 RPM	4000 RPM
SLG090	4:1	2078 (234.8)	698 (78.9)	530 (59.9)	460 (51.9)
	5:1	1798 (203.1)	896 (101.2)	680 (76.8)	591 (66.8)
	10:1	1126 (127.2)	1043 (117.8)	792 (89.5)	688 (77.7)
	16:1	2078 (234.8)	1057 (119.4)	803 (90.7)	698 (78.9)
	20:1	2078 (234.8)	1131 (127.8)	859 (97.1)	746 (84.3)
	25:1	1798 (203.1)	1452 (164.1)	1103 (124.6)	958 (108.2)
	40:1	2078 (234.8)	1392 (157.3)	1057 (119.4)	918 (103.7)
	50:1	1798 (203.1)	1787 (201.9)	1358 (153.4)	1179 (133.2)
	100:1	1126 (127.2)	1100 (124.3)	1100 (124.3)	1100 (124.3)
			1000 RPM	2000 RPM	3000 RPM
SLG115	4:1	4696(530.4)	1392 (157.3)	1132 (127.9)	1000 (112.9)
	5:1	4066 (459.4)	1445 (163.3)	1175 (132.8)	1040 (117.5)
	10:1	2545 (287.5)	1660 (187.6)	1350 (152.6)	1200 (135.6)
	16:1	4696 (530.4)	2112 (238.6)	1714 (193.0)	1518 (171.0)
	20:1	4696 (530.4)	2240 (253.1)	1840 (207.9)	1620 (183.0)
	25:1	4066 (459.4)	2350 (265.5)	1900 (214.7)	1675 (189.2)
	40:1	4696 (530.4)	2800 (316.4)	2240 (253.1)	2000 (225.9)
	50:1	4066 (459.4)	2900 (327.7)	2350 (265.5)	2100 (237.3)
	100:1	2545 (287.5)	2500 (282.5)	2500 (282.5)	2400 (271.2)

1 Stage 2 Stage

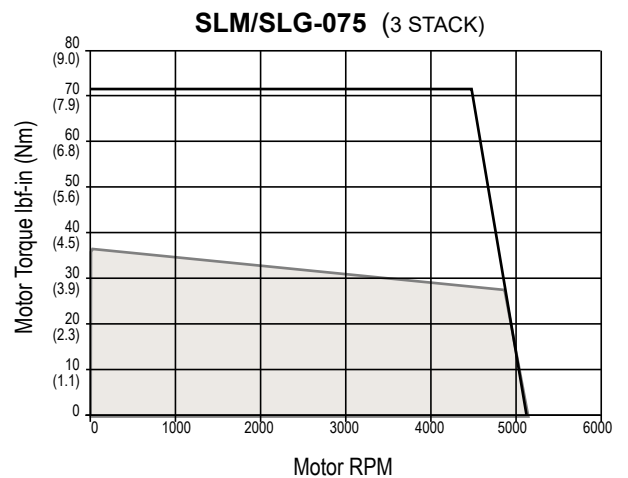
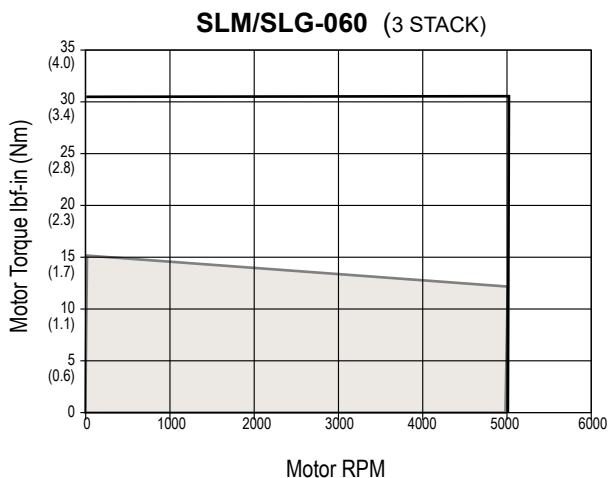
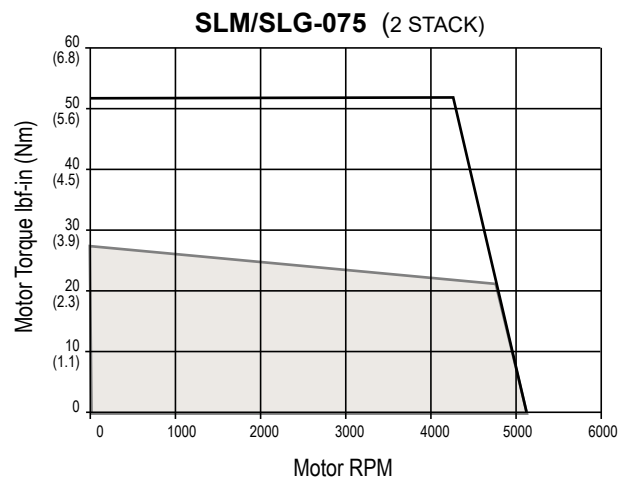
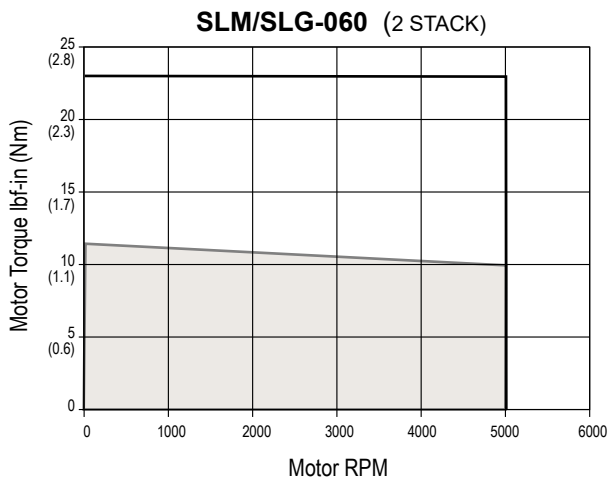
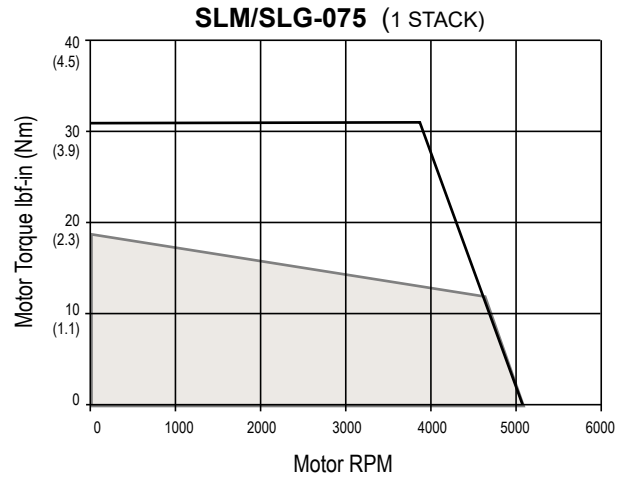
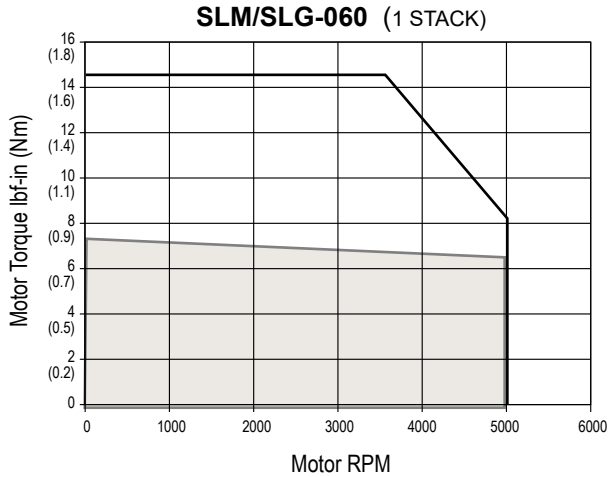
Motor and Gearmotor Weight

	SLM/G060			SLM/G075		SLM/G090			SLM/G115			SLM142	SLM180
	Motor	1 Stage	2 Stage	Motor	1 Stage	Motor	1 Stage	2 Stage	Motor	1 Stage	2 Stage	(gear stages not available on SLM142 and SLM180)	
1 Stack lbs (kg)	3.0 (1.4)	7.5 (3.4)	9.3 (2.4)	4.2 (1.9)	6.6 (3.0)	5.4 (2.4)	12.8 (5.8)	14.8 (6.7)	14.2 (6.4)	28 (12.7)	34 (15.4)	31 (14.0)	60 (27.2)
2 Stack lbs (kg)	4.1 (1.9)	8.6 (3.9)	10.4 (4.7)	6.0 (2.7)	8.4 (3.8)	7.8 (3.5)	15.2 (6.9)	17.2 (7.8)	22.0 (9.9)	35.8 (16.2)	41.8 (18.9)	39 (17.7)	82 (37.2)
3 Stack lbs (kg)	5.2 (2.4)	9.7 (4.4)	11.5 (5.2)	7.8 (3.5)	10.2 (4.6)	10.2 (4.6)	17.6 (7.9)	19.6 (8.9)	29.8 (13.5)	43.6 (19.8)	49.6 (22.5)	47 (21.3)	104 (47.2)
Brake		1.8 (0.8)		0.8 (0.4)			2.7 (1.2)			4.1 (1.9)		6.0 (2.7)	12 (5.4)

Speed and Torque Curves

These speed vs. torque curves represent approximate continuous torque ratings at the indicated rpms. Different types of servo amplifiers offer varying motor torque.

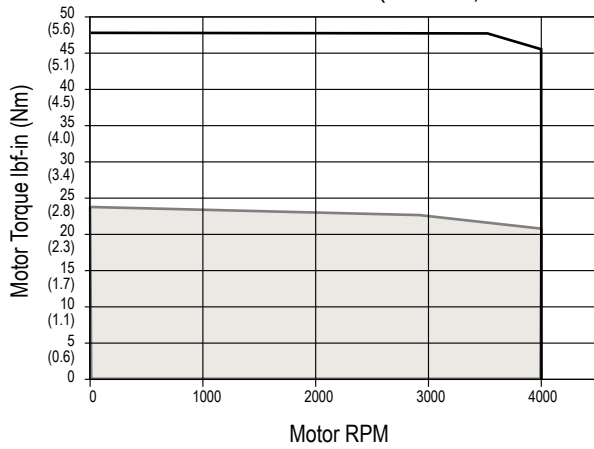
— Peak Torque
 ■ Continuous Torque



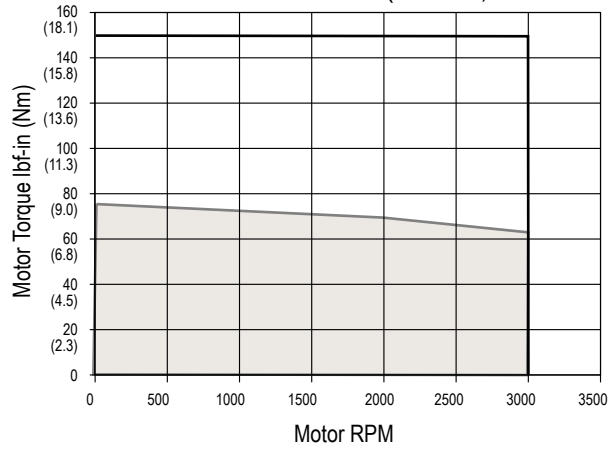
Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 1/4" on SLM/SLG060 and 10" x 10" x 3/8" on SLM/SLG075 at 25° C ambient. For gearmotors, divide speed by gear ratio; multiply torque by gear ratio and efficiency. Efficiencies: 1 Stage = 0.91, 2 Stage = 0.86

SLM /SLG Rotary Actuators

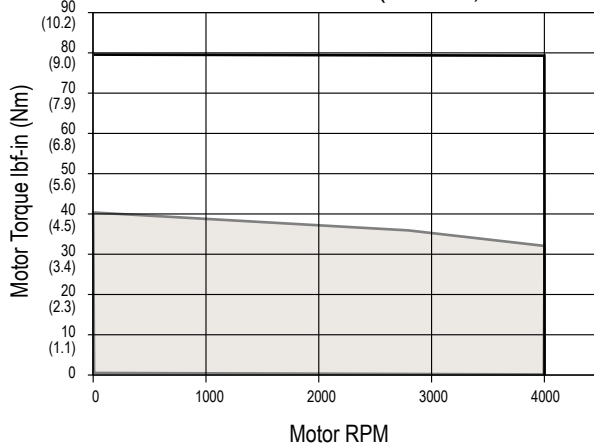
SLM/SLG-090 (1 STACK)



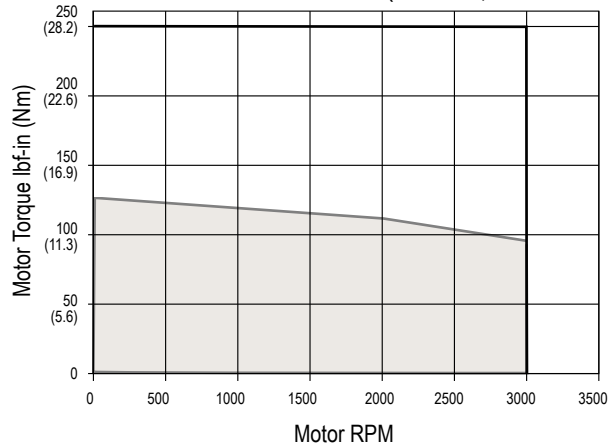
SLM/SLG-115 (1 STACK)



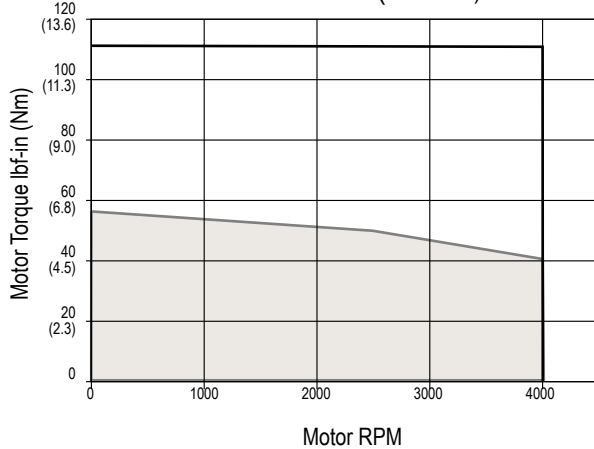
SLM/SLG-090 (2 STACK)



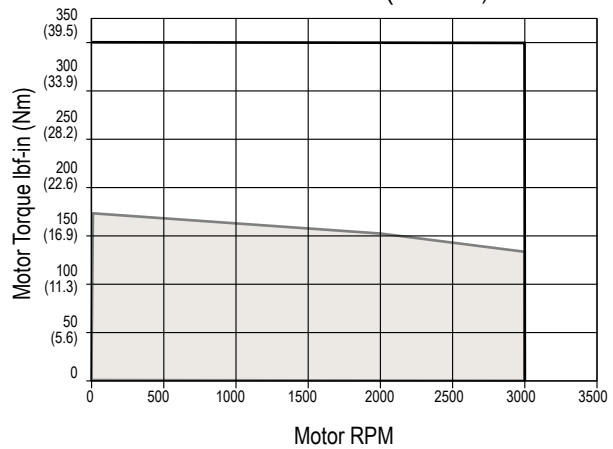
SLM/SLG-115 (2 STACK)



SLM/SLG-090 (3 STACK)



SLM/SLG-115 (3 STACK)

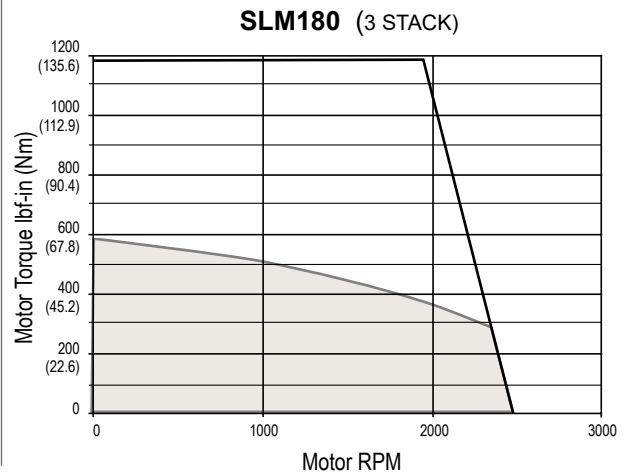
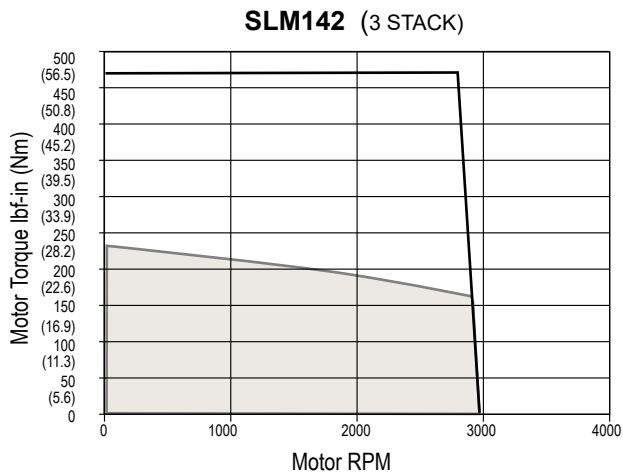
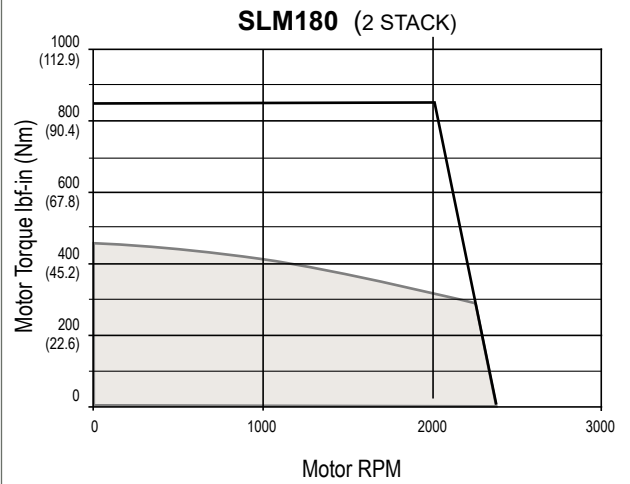
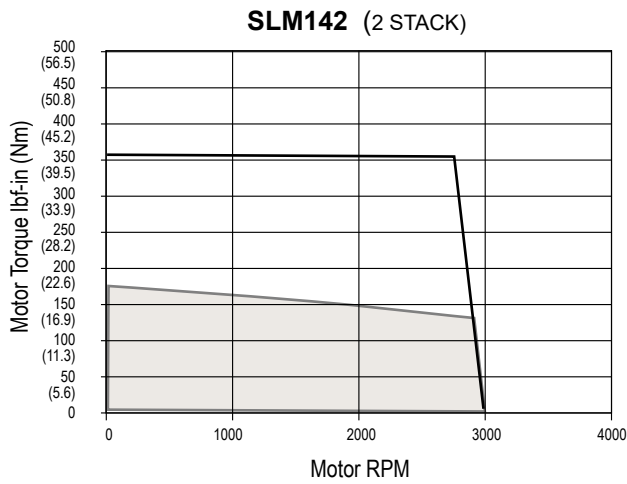
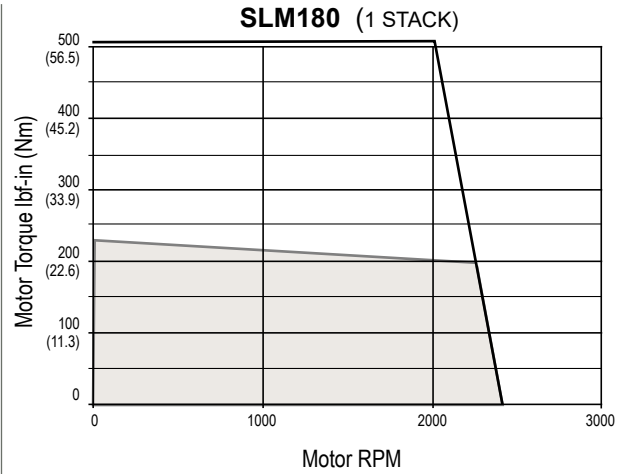
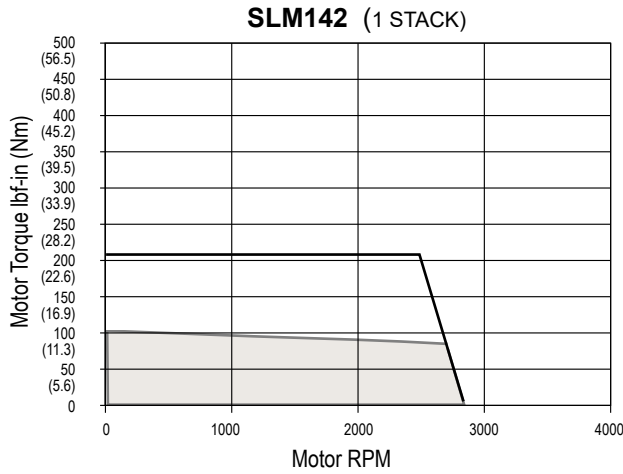


Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 3/8" on SLM/SLG090 and 12" x 12" x 1/2" on SLM/SLG115 at 25°C ambient. For gearmotors, divide speed by gear ratio; multiply torque by gear ratio and efficiency. Efficiencies: 1 Stage = 0.91, 2 Stage = 0.86

— Peak Torque



 Continuous Torque

SLM /SLG Rotary Actuators



Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2" on SLM142 at 25°C ambient.

Test data derived using NEMA recommended aluminum heatsink 16" x 16" x 1" on SLM180 at 25°C ambient

 Peak Torque
 Continuous Torque

Options

Motor Speed

All Exlar T-LAM motors and actuators carry a standard motor speed designator (see chart). This is representative of the standard base speed of the motor for the selected bus voltage.

If the model number is created and the location for the motor speed designator is left blank, this is the base speed to which the motor will be manufactured. The model number can also be created including this standard speed designator.

Designator	Base Speed	Motor Series
-50	5000 rpm	SLM/SLG060
-40	4000 rpm	SLM/SLG075
-40	4000 rpm	SLM/SLG090
-30	3000 rpm	SLM/SLG115
-24	2400 rpm	SLM142, SLM180

Motor Stators

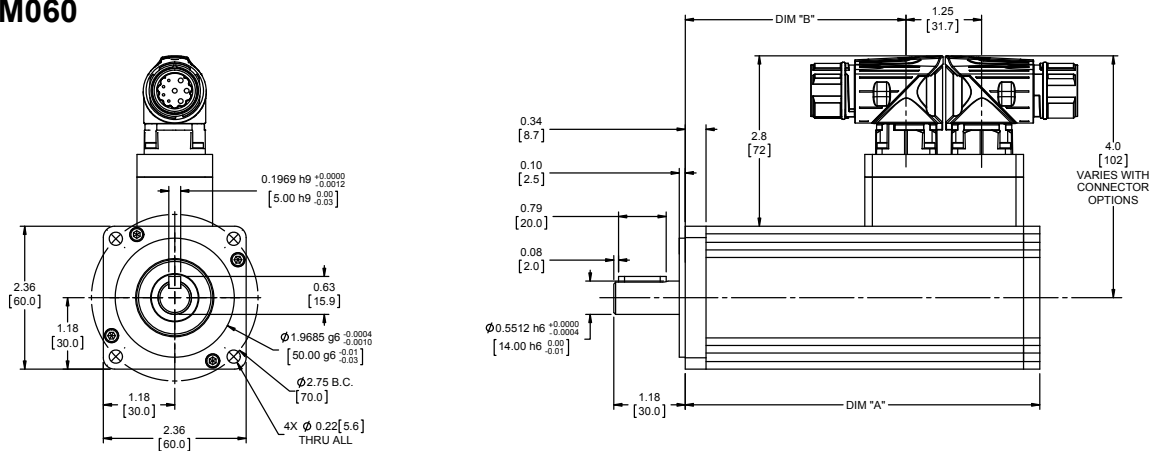
SLM/SLG motor options are described with a 3 digit code. The first digit calls out the stack length, the second digit signifies the rated bus voltage, and the third digit identifies the number of poles of the motor. Refer to the mechanical/electrical specifications for motor torque and actuator rated force.

8 Pole, Class 180 H

1 Stack		2 Stack		3 Stack	
118	115 Vrms	218	115 Vrms	318	115 Vrms
138	230 Vrms	238	230 Vrms	338	230 Vrms
158	400 Vrms	258	400 Vrms	358	400 Vrms
168	460 Vrms	268	460 Vrms	368	460 Vrms

Dimensions

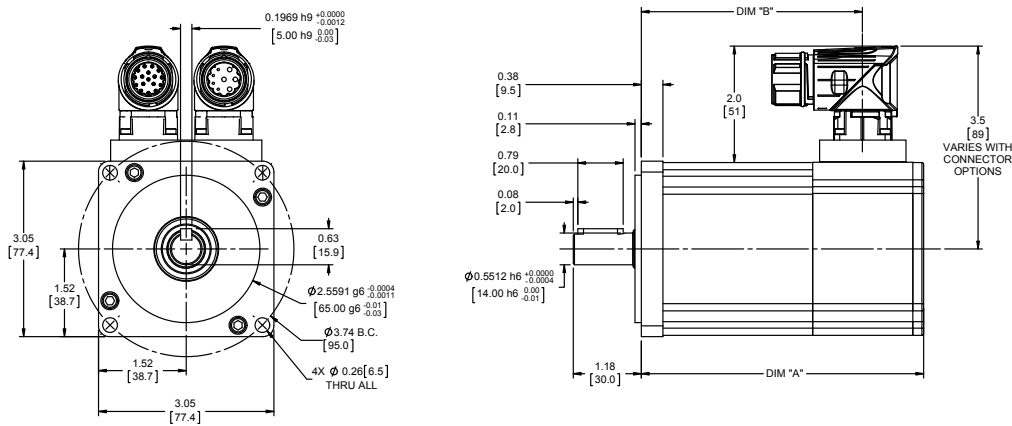
SLM060



DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	4.61 (117.1)	5.86 (148.9)	7.11 (180.6)
B	2.40 (61.1)	3.65 (92.8)	4.90 (124.6)

Add 1.02 inches (25.9 mm) to Dimensions A and B if ordering a brake.
Face plate edge is not intended for alignment of shaft (use pilot)

SLM075



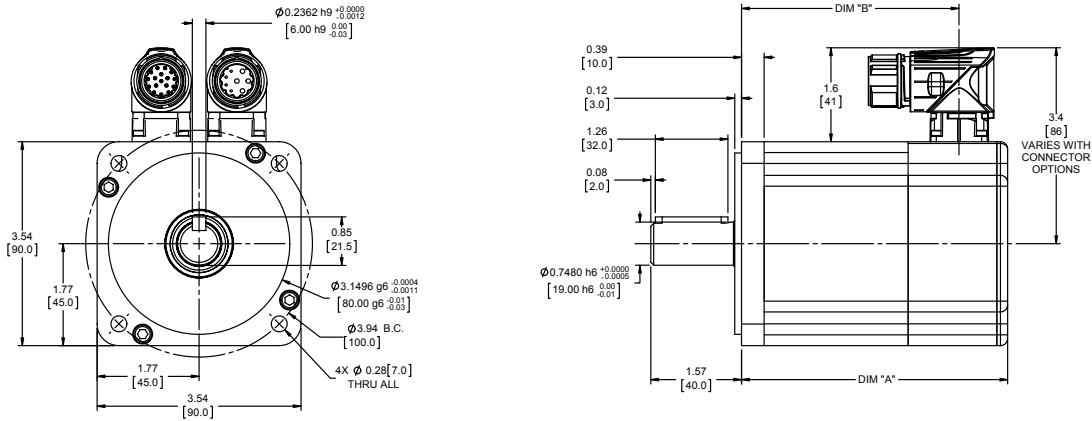
DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	4.90 (124.5)	5.90 (149.9)	6.90 (175.3)
B	3.84 (97.6)	4.84 (123.0)	5.84 (148.4)

Add 1.28 inches (32.5 mm) to Dimensions A and B if ordering a brake.
Face plate edge is not intended for alignment of shaft (use pilot)

Due to the size of many absolute encoders, the selection of such feedback results in a larger package size than is shown in drawings. Consult Exlar for details, or refer to the drawings provided after receipt of order.

SLM /SLG Rotary Actuators

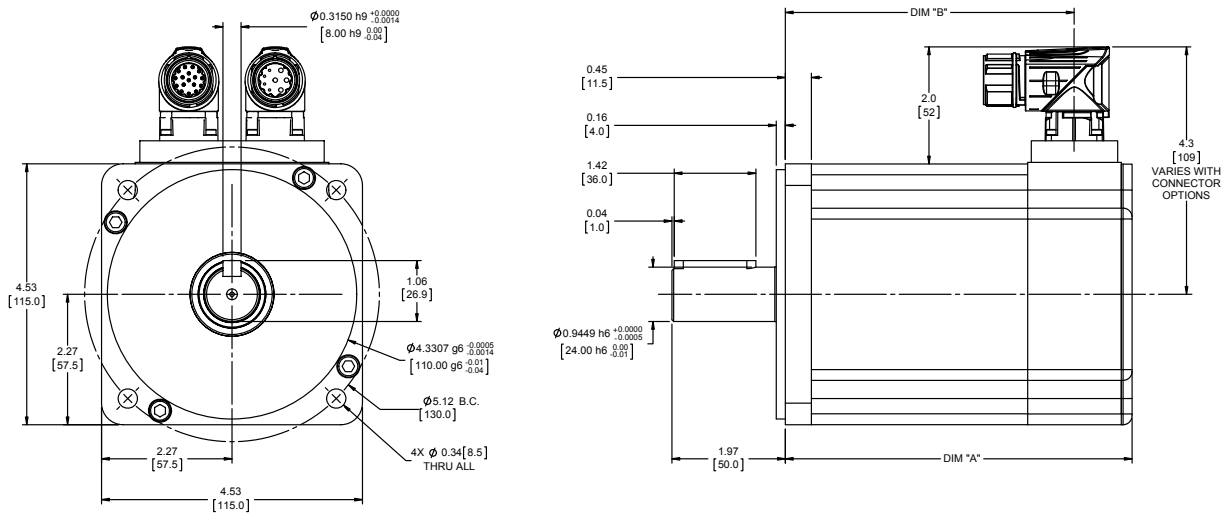
SLM090



DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	4.65 (118.1)	5.65 (143.5)	6.65 (168.9)
B	3.81 (96.8)	4.76 (121.0)	5.81 (147.6)

Add 1.31 inches (33.3 mm) to Dimensions A and B if ordering a brake.
Face plate edge is not intended for alignment of shaft (use pilot)

SLM115

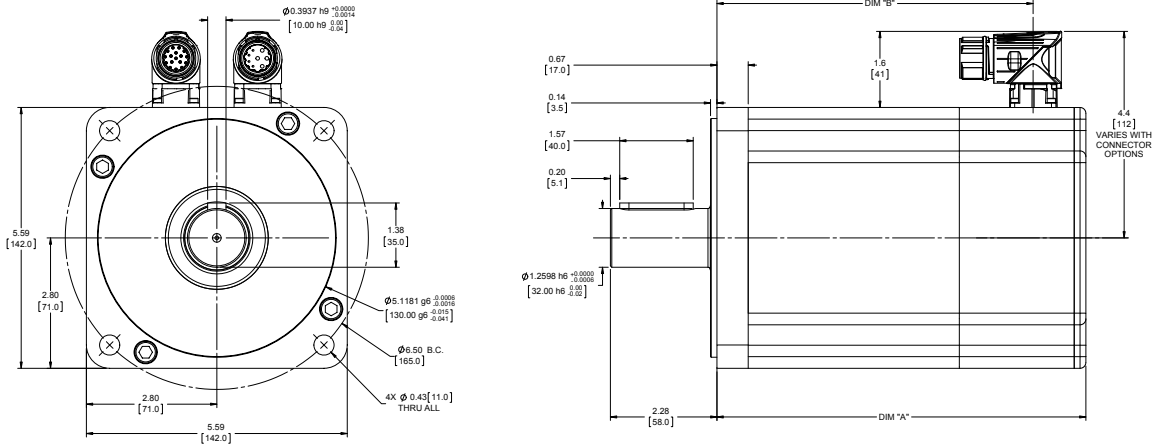


DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	6.02 (152.9)	8.02 (203.7)	10.02 (254.5)
B	5.02 (127.5)	7.02 (178.3)	9.02 (229.1)

Add 1.73 inches (43.9 mm) to Dimensions A and B if ordering a brake.
Face plate edge is not intended for alignment of shaft (use pilot)

Due to the size of many absolute encoders, the selection of such feedback results in a larger package size than is shown in drawings. Consult Exlar for details, or refer to the drawings provided after receipt of order.

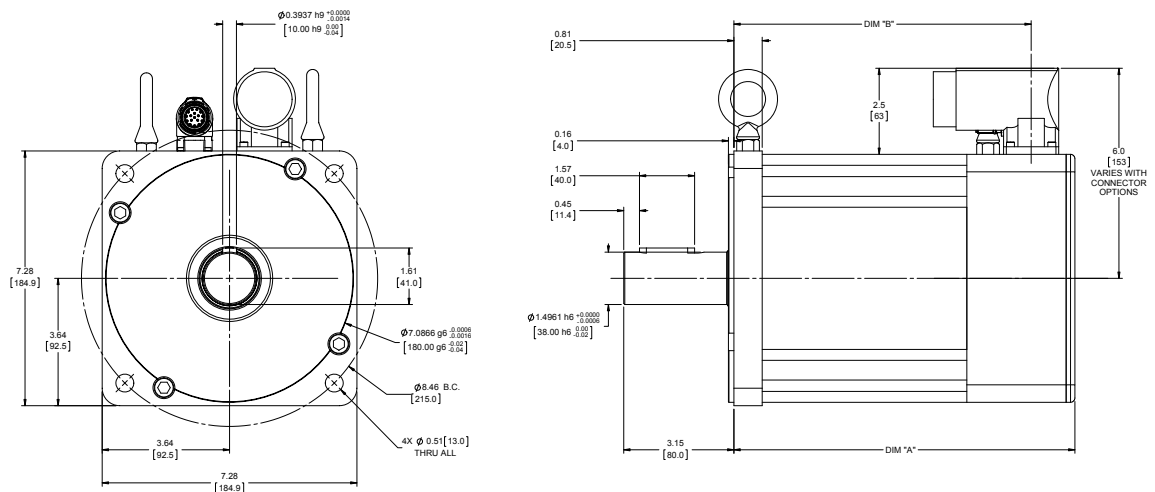
SLM142



DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	7.87 (199.9)	9.62 (244.3)	11.37 (288.8)
B	6.75 (171.3)	5.50 (139.6)	10.25 (260.2)

Add 1.66 inches (42.2 mm) to Dimensions A and B if ordering a brake.
Face plate edge is not intended for alignment of shaft (use pilot)

SLM180



DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	9.74 (247.4)	12.24 (310.9)	14.74 (374.4)
B	8.49 (215.6)	10.99 (279.1)	13.49 (342.6)

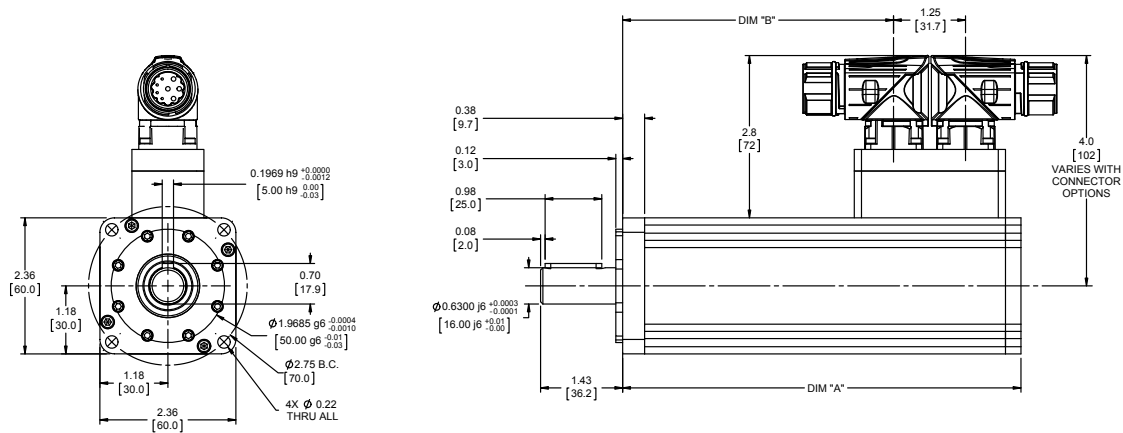
Add 1.90 inches (48.3 mm) to Dimensions A and B if ordering a brake.
Face plate edge is not intended for alignment of shaft (use pilot)

Due to the size of many absolute encoders, the selection of such feedback results in a larger package size than is shown in drawings. Consult Exlar for details, or refer to the drawings provided after receipt of order.

Pre-sale drawings and models are representative and are subject to change. Certified drawings and models are available for a fee. Consult your local Exlar representative for details.

SLM /SLG Rotary Actuators

SLG060

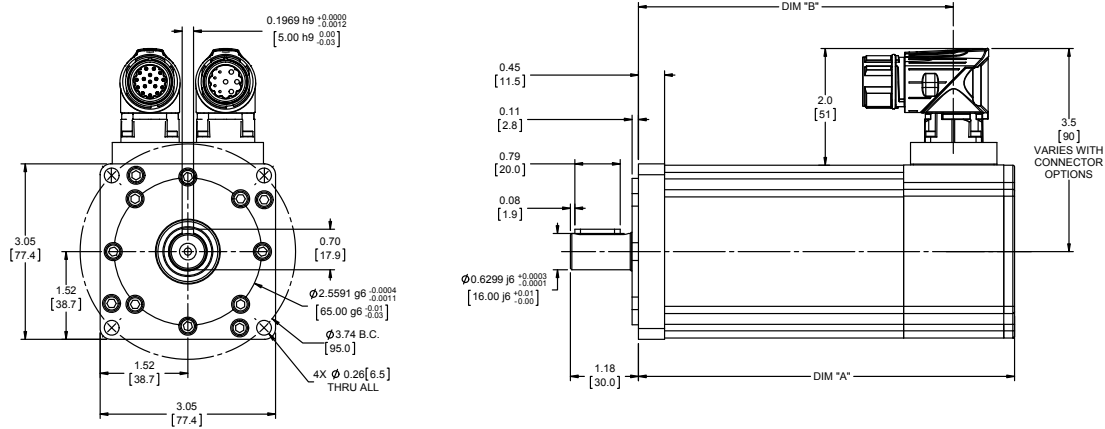


1 Stage Gearhead			
DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	6.92 (175.6)	8.17 (207.4)	9.42 (239.1)
B	4.71 (119.6)	5.96 (151.4)	7.21 (183.1)

2 Stage Gearhead			
DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	7.96 (202.2)	9.21 (233.9)	10.46 (265.7)
B	5.75 (146.2)	7.00 (177.9)	8.25 (209.7)

Add 1.02 inches (25.9 mm) to Dimensions A and B if ordering a brake.
Face plate edge is not intended for alignment of shaft (use pilot)

SLG075



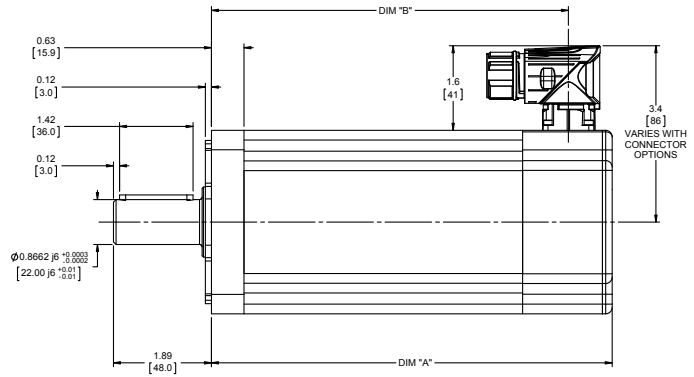
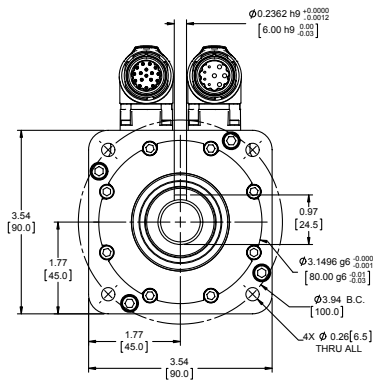
1 Stage Gearhead			
DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	6.53 (165.9)	7.53 (191.3)	8.53 (216.7)
B	5.47 (139.0)	6.47 (164.4)	7.47 (189.8)

Add 1.23 inches (31.2 mm) to Dimensions A and B if ordering a brake.
Face plate edge is not intended for alignment of shaft (use pilot)

Due to the size of many absolute encoders, the selection of such feedback results in a larger package size than is shown in drawings. Consult Exlar for details, or refer to the drawings provided after receipt of order.

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SLG090

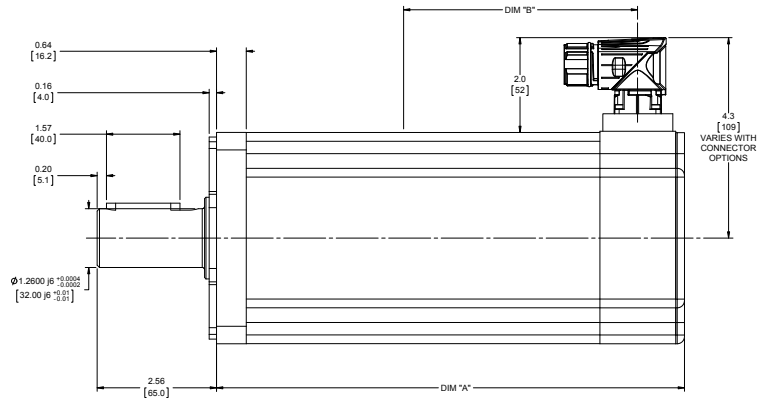
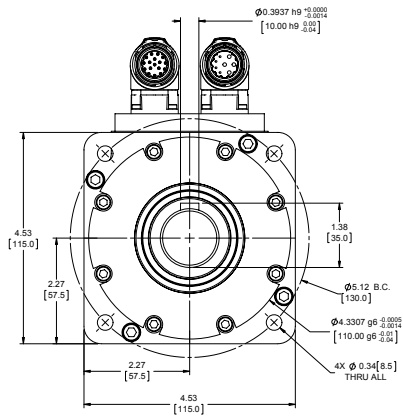


1 Stage Gearhead			
DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	7.76 (197.1)	8.76 (222.5)	9.76 (247.9)
B	6.92 (175.8)	7.92 (201.2)	8.92 (226.6)

2 Stage Gearhead			
DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	9.03 (229.2)	10.03 (254.6)	11.03 (280.0)
B	8.19 (207.9)	9.19 (233.3)	10.19 (258.7)

Add 1.31 inches (33.3 mm) to Dimensions A and B if ordering a brake.
Face plate edge is not intended for alignment of shaft (use pilot)

SLG115



1 Stage Gearhead			
DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	10.03 (254.8)	12.03 (305.6)	14.03 (256.4)
B	9.03 (255.0)	11.03 (280.2)	13.03 (331.0)

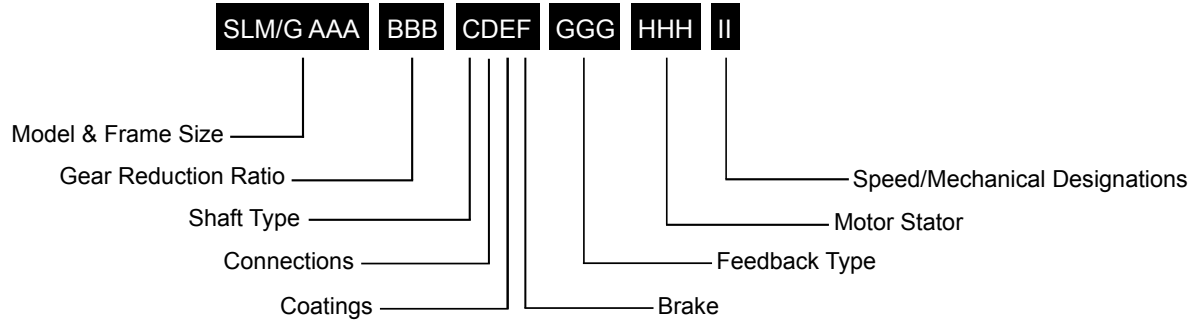
2 Stage Gearhead			
DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	11.64 (295.7)	13.64 (346.5)	15.64 (397.3)
B	10.64 (270.3)	12.64 (321.1)	14.64 (372.1)

Add 1.73 inches (43.9 mm) to Dimensions A and B if ordering a brake.
Face plate edge is not intended for alignment of shaft (use pilot)

Due to the size of many absolute encoders, the selection of such feedback results in a larger package size than is shown in drawings. Consult Exlar for details, or refer to the drawings provided after receipt of order.

Pre-sale drawings and models are representative and are subject to change. Certified drawings and models are available for a fee. Consult your local Exlar representative for details.

Ordering Information



SLM/G = Model Series

SLG = SLG Series Servo Gear Motor
 SLM = SLM Series Servo Motor
 (No Gear Reduction)

AAA = Frame Size

060 = 60 mm
 075 = 75 mm
 090 = 90 mm
 115 = 115 mm
 142 = 142 mm, (SLM only)
 180 = 180 mm, (SLM only)

BBB = Gear Reduction Ratio

Blank = SLM

Single reduction ratio

004 = 4:1
 005 = 5:1
 010 = 10:1

Double reduction ratio (N/A on 075 mm)

016 = 16:1
 020 = 20:1
 025 = 25:1
 040 = 40:1
 050 = 50:1
 100 = 100:1

C = Shaft Type

K = Keyed

D = Connections

I = Exlar standard M23 style
 M = Manufacturer's connector ¹

E = Coating Options

G = Anodized Aluminum (standard)

F = Brake Options

B = Brake
 S = Standard no brake

GGG = Feedback Type

See page 164 for detailed information.

HHH = Motor Stator – All 8 Pole ²

118 = 1 stack	115 Vrms	158 = 1 stack	400 Vrms
218 = 2 stack		258 = 2 stack	
318 = 3 stack		358 = 3 stack	
138 = 1 stack	230 Vrms	168 = 1 stack	460 Vrms
238 = 2 stack		268 = 2 stack	
338 = 3 stack		368 = 3 stack	

II = Optional Speed and Mechanical Designations

24 = 2400 rpm, SLM142 & 180
 30 = 3000 rpm, SLM/G115
 40 = 4000 rpm, SLM075, SLM/G090
 50 = 5000 rpm, SLM/G060

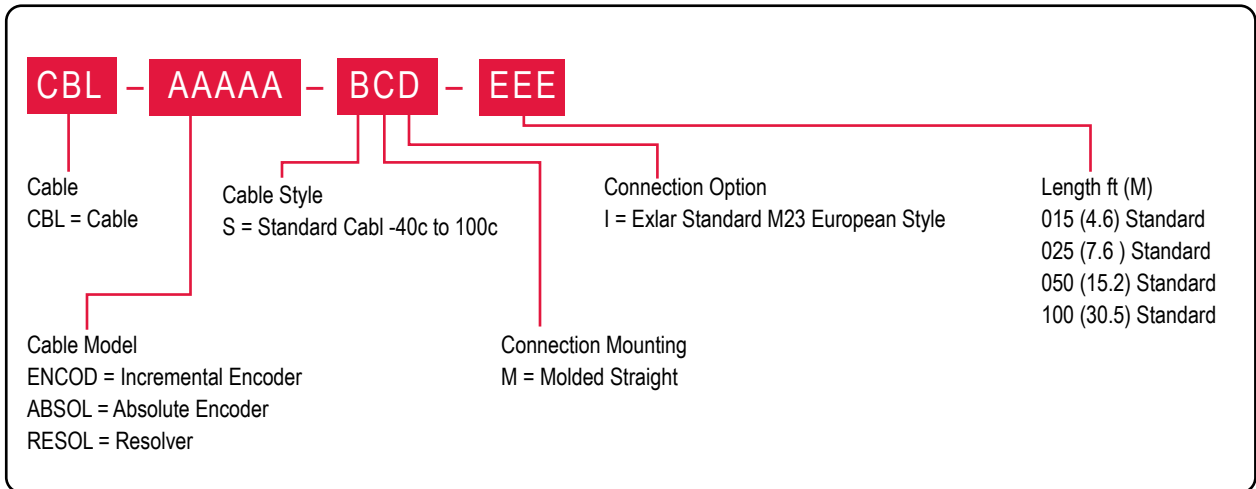
NOTES:

1. Available as described in Feedback Types.
2. See page 153 for explanation of voltage, speed, stack and optimized stator options.

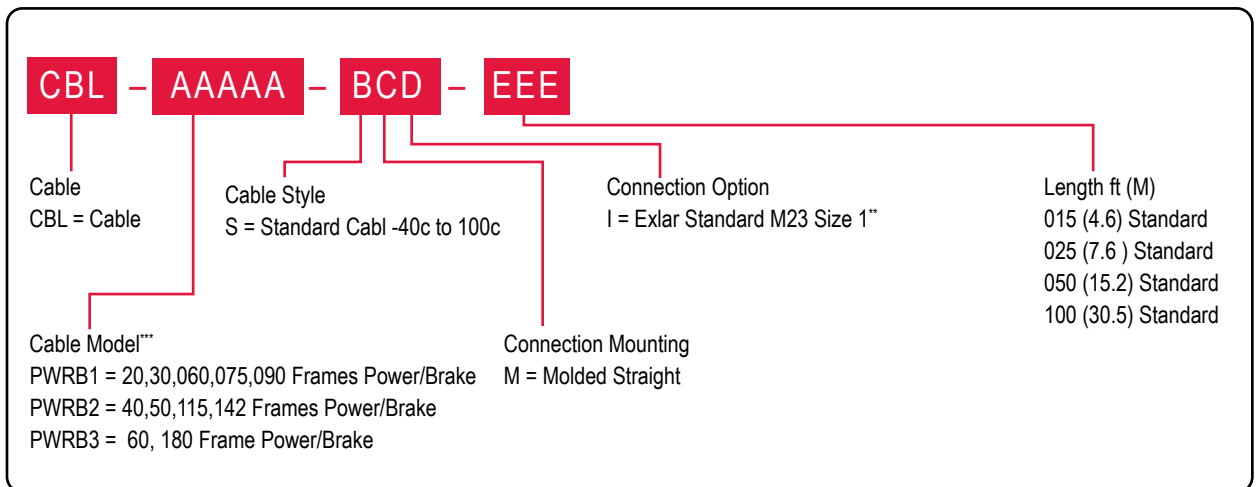


For options or specials not listed above or for extended temperature operation, please contact Exlar

Feedback Cable Configuration - e.g. CBL-ENCOD-SMI-015



Power Cable Configuration - e.g. CBL-PWRB1-SMI-015



All Exlar cables rated IP65 when mated to actuator.

* Non-standard options – require longer lead times.

** PWRB3 uses M40 size 1.5.

*** Special stator winding may require a special power cable.

Manufacturers Feedback Cable Selection Guide

Amplifier/Drive Selected	Feedback Selected	Manufacturers Part Number
Allen-Bradley/Rockwell: All Drives	RA3 RA1, RA2, RA4	2090-CFBM7DF-CDAxyy 2090-CFBM7DF-CEAxyy
B&R Automation: All Drives	BR1 BR2	8CRxxx.12-1 8CExxx.12-1
Control Techniques: Unidrive SP/Epsilon EP	CT1/CT3 EM2/EM5 CT4/CT7	SSBCABXXXX UFCSXXX SIBAAAXXXX SRBBBBXXXX
Unidrive M	CT5 CT5	SRBBABXXXX
Control Techniques/Epsilon	CT4/CT7 EM2/EM5	SIBAEAXXXX CFCSXXX
Elau: All Drives	EU1/EU4	SH Series Absolute Encoder Cable
Indramat/Bosch-Rexroth: DKC Series/DIAX	IN6 IN7/IN8	IKS4374 RKG4200
IndraDrive		
Kollmorgen/Danaher: All Drives	KM4 KM5 KM6	VF-SB4474N-XX VF-RA2474N-XX CF-CB7374N-XX
Lenze/AC Tech: All Drives	LZ1 LZ5 LZ6	MCS Series Absolute Encoder Cable MCS Series Resolver Cable MCS Series Incremental Encoder Cable
Parker Compumotor: All Drives	PC6 PC7 PC8 PC9/ PC0	SMH Series Incremental Encoder Cable SMH Series Resolver Cable COMPAX3 F-2C1-xx or Aries F-1A1-xx F-2B1-xx
Stober Drives: FDS/MDS 5000	SB3	Stober Absolute Encoder Cable
Siemens: 611U/Masterdrives/SMC20	SM2 SM3/SM4 SM5	6FX5002-2CF02-.... 6FX5002-2EQ10-.... 6FX5002-2CA31-....
SEW/Eurodrive: All Drives	SW1 SW3	CMP Series Resolver Cable CMP Series Absolute Encoder Cable

SLM /SLG Rotary Actuators

Models		SLM/SLG060, SLM/SLG090		
Amplifier/Drive Selected	Feedback Selected	Power only 4 wire	Power + Brake/Therm	Brake Cable
Allen-Bradley/Rockwell: All Drives	RA1/RA2/RA3/RA4 AB8/AB9/ABB	2090-CPWM7DF-16Axyy	2090-CPBM7DF-16Axyy	N/A
B&R Automation: All Drives	BR1/BR2	N/A	8CMxxx.12-1	N/A
Control Techniques: All Drives	CT1/CT3/CT4/CT5/CT7 EM2/EM5	MSBAAA CMDS	MBBAAA N/A	N/A CBMS
Indramat/Bosch-Rexroth: DKC Series/DIAX IndraDrive	IN1/IN5/IN6 IN7/IN8	N/A N/A	MKD/MHD Power Cable Size 1 MSK Power Cable Size 1	N/A N/A
Kollmorgen/Danaher: All Drives	KM4/KM5/KM6	N/A	6 Amp - VP-508CFAN-XX 12 Amp - VP-508CFAN-XX 20 Amp - VP-508DFAN-XX	N/A
Lenze/AC Tech: All Drives	LZ1/LZ5/LZ6	N/A	MCS Power Cable Size 1	N/A
Parker Compumotor: All Drives	PC6/PC7 PC8/PC9/PC0	N/A N/A	SMH Power Cable Size 1 P-3B1-xx	N/A N/A
Stober Drives: FDS/MDS 5000	SB3	N/A	Stober Power Cable Size 1	N/A
Siemens: All Drives with flying leads	SM2/SM3/SM4/SM5		6FX5002-5DA01-....	N/A
SEW/Eurodrive: All Drives	SW1/SW3	N/A	CMP Power Cable Size 1	N/A

*If stator current draw exceeds cable connector rating, a larger connector will be provided. Please note: Euro style connectors are size 1.5 M40 connectors. If the manufacturer does not offer a size 1.5 M40 power cable, an Exlar Power Cable must be purchased.

SLM /SLG Rotary Actuators

Models	SLM/SLG115, SLM142			SLM180		
Amplifier/Drive Selected	Power only 4 wire	Power + Brake/Therm	Brake Cable	Power only 4 wire	Power + Brake/Therm	Brake Cable
Allen-Bradley/ Rockwell: All Drives	2090-CPWM7DF- 14Axyy	2090-CPBM7DF-14Axyy	N/A	2090-CPWM7DF-10Axyy	2090-CPBM7DF-10Axyy	N/A
B&R Automation: All Drives	N/A	8CMxxx.12-3	N/A	N/A	8CMxxx.12-5	N/A
Control Techniques: All Drives	MSBAAA CMMS	MBBAAA N/A	N/A CBMS	PSBxB CMLS	PBBxB N/A	N/A CBMS
Indramat/ Bosch-Rexroth: DKC Series/DIAX IndraDrive	N/A N/A	MKD/MHD Power Cable Size 1 MSK Power Cable Size 1	N/A N/A	N/A N/A	MKD/MHD Power Cable Size 1.5 MSK Power Cable Size 1.5	N/A N/A
Kollmorgen/ Danaher: All Drives	N/A	6 Amp - VP-508CFAN-XX 12 Amp - VP-508CFAN-XX 20 Amp - VP-508DFAN-XX	N/A	N/A	Under 24 AMP use CP-508-ENBN-XXX Over 24 AMP Contact Kollmorgen Vendor	N/A
Lenze/AC Tech: All Drives	N/A	MCS Power Cable Size 1	N/A	N/A	MCS Power Cable Size 1.5	N/A
Parker Compumotor: All Drives	N/A N/A	SMH Power Cable Size 1 P-4B1-xx	N/A N/A	N/A N/A	SMH Power Cable Size 1.5 P-6B2-xx	N/A N/A
Stober Drives: FDS/ MDS 5000	N/A	Stober Power Cable Size 1	N/A	N/A	Stober Power Cable Size 1.5	N/A
Siemens: All Drives with flying leads		6FX5002-5DA11-....	N/A		6FX5002-5DA61-....	N/A
SEW/Eurodrive: All Drives	N/A	CMP Power Cable Size 1	N/A	N/A	CM Power Cable Size 1.5	N/A

Feedback Types for SLG, SLM

(Also specify the Amplifier/Drive Model being used when ordering)

- Standard Incremental Encoder – 2048 line (8192 cts) per rev. index pulse, Hall commutation, 5VDC
- Standard Resolver – Size 15, 1024 line (2048 cts) per rev. two pole resolver
- Motor files for use with select Emerson/CT, Rockwell /AB and Danaher/Kollmorgen Drives are available at www.exlar.com

Allen-Bradley/Rockwell: (Note: AB8, AB9 and ABB callouts are available only on spare/replacement actuators that have been previously ordered. For all new configurations using a Rockwell drive, please select from the options below. Consult Exlar for integration questions)³

Note: RA1, RA2, RA3, and RA4 callouts are not available for SLM/G motors.

- RA1 = SICK Hiperface SKM36 multi-turn absolute encoder. MPL Type V feedback (128 sin/cos) and Type 7 SpeedTec connectors and wiring when using the “M” connector option. 20 and 30 frame sizes only. (Formerly ABB)^{1,4}
- RA2 = SICK Hiperface SRM50 multi-turn absolute encoder. MPL Type M feedback (1024 sin/cos) and Type 7 SpeedTec connectors and wiring when using the “M” connector option. 40, 50 and 60 frame sizes only. (Formerly AB9)^{1,4}
- RA3 = Standard incremental encoder. MPL Type M feedback (2048 line) and Type 7 SpeedTec connector and wiring when using the “M” connector option. (Formerly AB8)⁴
- RA4 = Standard Resolver. MPL Type R feedback (4 pole) and Type 7 SpeedTec connectors and wiring when using the “M” connector option. (Formerly AB6)⁴

Advanced Motion Control:

- AM1 = Standard Incremental Encoder
- AM2 = Encoder 1000 line, w/commutation, 5 VDC
- AM3 = Standard Resolver
- AM5 = Encoder 5000 line, w/commutation, 5 VDC

Baldor:

- BD2 = Std Resolver – BSM motor wiring w/M23 connectors for ‘M’ option
- BD3 = Std Incremental Encoder – BSM motor wiring w/M23 connectors for ‘M’ option

Beckhoff:

- BE2 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – AM5XX motor wiring w/M23 euro connectors for ‘M’ option

B&R Automation:

- BR1 = Standard Resolver
- BR2 = EnDat Heidenhain EQN1125/1325 multi-turn absolute encoder – 8LS/8LM motor wiring w/M23 euro connectors for ‘M’ option

Copley Controls:

- CO1 = Standard Incremental Encoder
- CO2 = Standard Resolver

Control Techniques:

- CT1 = SICK Hiperface SRM050 multi-turn absolute encoder – 40-50-60 Frame Size. FM/UM/EZ motor wiring w/M23 euro connectors for ‘M’ option
- CT3 = SICK Hiperface SKM036 multi-turn absolute encoder – 20-30 Frame Size. FM/UM/EZ motor wiring w/M23 euro connectors for ‘M’ option
- CT4 = Standard Incremental Encoder – FM/UM/EZ motor wiring w/M23 euro connectors for ‘M’ option
- CT5 = Std Resolver – FM/UM/EZ motor wiring w/M23 euro connectors for ‘M’ option
- CT7 = Encoder 5000 line, with commutation, 5 VDC – FM/UM/EZ motor wiring w/M23 euro connectors for ‘M’ option
- CT9 = Unidrive SP with EnDat Heidenhain EQN1125 multi-turn absolute encoder w/M23 connectors

Elmo Motion Control:

- EL1 = Standard Resolver
- EL2 = Standard Incremental Encoder
- EL3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder

Control Techniques:

- EM2 = Std Incremental Encoder – NT motor wiring w/MS connectors for ‘M’ option
- EM5 = Encoder 5000 line, with commutation, 5 VDC – NT motor wiring w/MS connectors for ‘M’ option

Elau:

- EU1 = SICK Hiperface SRM050 multi-turn absolute encoder – 40-50-60 Frame Size. SH motor wiring w/MS connectors for ‘M’ option
- EU4 = SICK Hiperface SKM036 multi-turn absolute encoder – 20-30 Frame Size. SH motor wiring w/MS connectors for ‘M’ option.

Exlar:

- EX4 = Standard Resolver
- EX5 = Standard Resolver with PT1000 thermistor
- EX6 = EnDat Heidenhain EQN1125 multi-turn absolute encoder
- EX7 = Incremental encoder, 5000 line with commutation, 5Vdc
- EX8 = SICK Hiperface SRM50 multi-turn absolute encoder

Indramat/Bosch-Rexroth:

- IN6 = Std Resolver – MKD/MHD motor wiring w/M23 euro connectors for ‘M’ option
- IN7 = SICK Hiperface SKM036 multi-turn absolute encoder – MSK motor wiring w/M23 euro connectors for ‘M’ option – plug & play option
- IN8 = Indradrive EnDat Heidenhain EQN1125 multi-turn absolute w/M23 connectors

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SLM /SLG Rotary Actuators

Kollmorgen/Danaher:

KM4 = EnDat Heidenhain EQN1325 multi-turn absolute encoder (Sine Encoder)– AKM motor wiring w/M23 Intercontec euro connectors for 'M' option

KM5 = Standard Resolver – AKM motor wiring w/M23 Intercontec euro connectors for 'M' option

KM6 = Standard Incremental Encoder – AKM motor wiring w/ M23 Intercontec euro connectors for 'M' option

Lenze/AC Tech:

LZ1 = SICK Hiperface SRM050 multi-turn absolute encoder – MCS motor wiring w/M23 euro connectors for 'M' option

LZ5 = Standard Resolver – MCS motor wiring w/ M23 euro connectors for 'M' option

LZ6 = Standard Incremental Encoder – MCS motor wiring w/ M23 euro connectors for 'M' option

Parker Compumotor:

PC6 = Std Incremental Encoder – SMH motor wiring w/M23 connectors for 'M' option – European only

PC7 = Std Resolver – SMH motor wiring w/M23 connectors for 'M' option – European only

PC8 = Standard Incremental Encoder – MPP series motor wiring w/PS connectors for 'M' option – US Only

PC9 = SICK Hiperface SRM050 multi-turn absolute encoder – MPP motor wiring w/PS connectors for 'M' option – US Only

PC0 = Standard Resolver – MPP motor wiring w/PS connectors for 'M' option – US Only

Schneider Electric:

SC2 = SICK Hiperface SKM036 multi-turn absolute encoder – BSH motor wiring w/M23 euro connectors for 'M' option

Stober Drives:

SB3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – ED/EK motor wiring w/M23 euro connectors for 'M' option

SB4 = Standard Resolver ED/EK motor wiring W/23 connector for "M" option

Siemens:

SM2 = Standard Resolver – 1FK7 motor wiring w/M23 connectors for 'M' option

SM3 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 40-50-60 Frame Size. 1FK7 motor wiring w/M23 euro connectors for 'M' option

SM4 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – 20-30 Frame Size. 1FK7 motor wiring w/M23 euro connectors for 'M' option

SM9 = Siemens Heidenhain EQN1135 Endat 2.2 (23 bit) multi-turn absolute. 1KF7 motor wiring w/M23 connectors

SEW/Eurodrive:

SW1 = Standard Resolver – CM motor wiring w/ M23 euro connectors for 'M' option

SW3 = Hiperface Stegmann SRM050 multi-turn absolute encoder – CM motor wiring w/ M23 euro connectors for 'M' option

NOTES:

1. Not compatible with Kinetix 300 Drives.
2. N/A with holding brake unless application details are discussed with your local sales representative.
3. All rotary motors to be used with Kinetix or Sercos based systems will require prior approval from Rockwell Automation.
4. Not available with rotary motors

Warranty and Limitations of Liability

WARRANTY AND LIMITATION OF LIABILITY: Please see our warranty on our website here: <https://www.cw-actuation.com/en-gb/about/terms-conditions> for details.

USA & CANADA

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The logo for EXLAR, featuring the word "EXLAR" in a bold, stylized, black font. The letter "X" is uniquely designed with a diagonal slash through it. A registered trademark symbol (®) is located at the top right of the "R".

www.exlar.com

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